

**Fall 2021**

# ADVANCED TOPICS IN COMPUTER VISION

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<https://vita-group.github.io/>

# What is Visual Recognition?

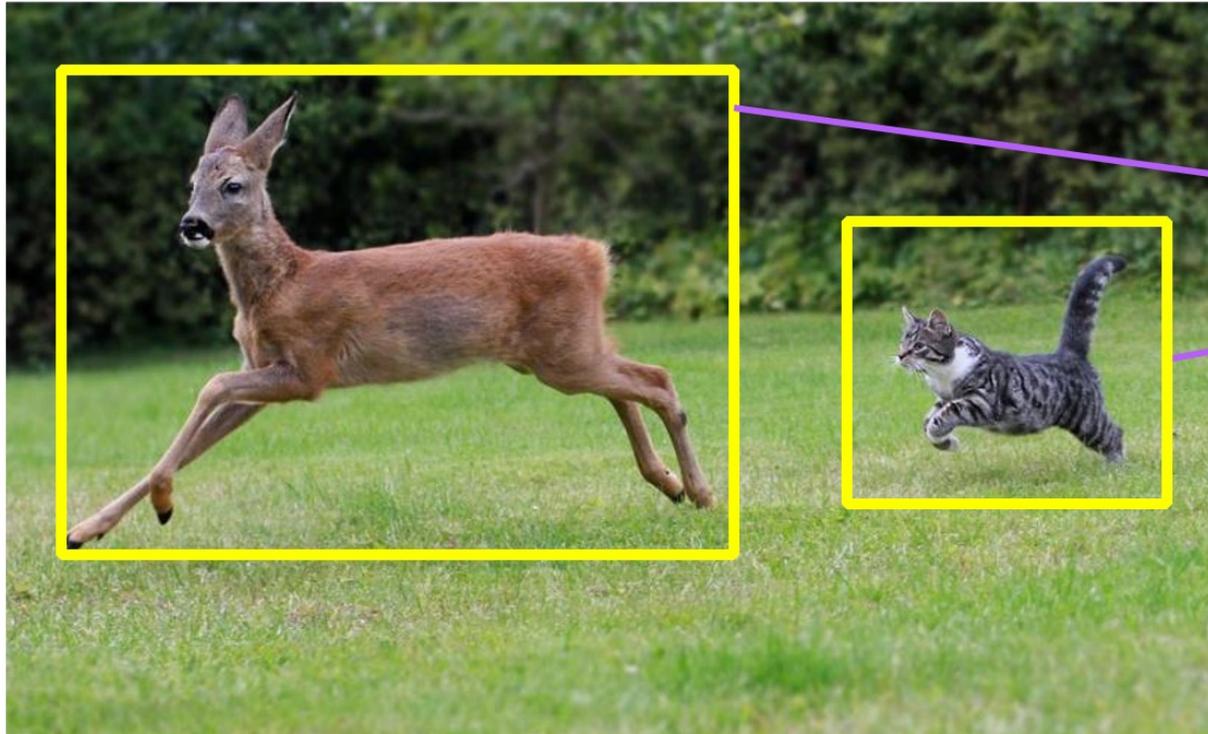
Image tagging



deer  
cat  
trees  
grass

# What is Visual Recognition?

## Object detection



deer

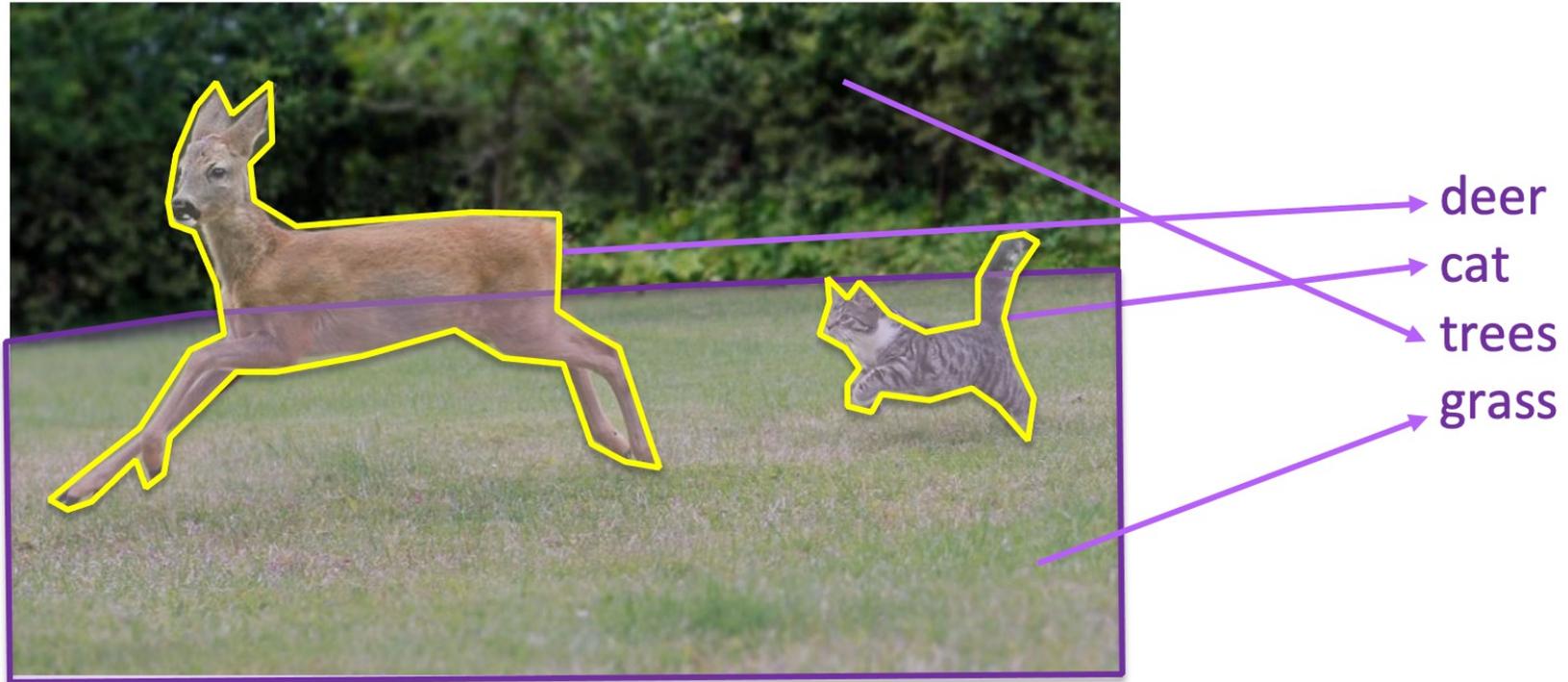
cat

trees

grass

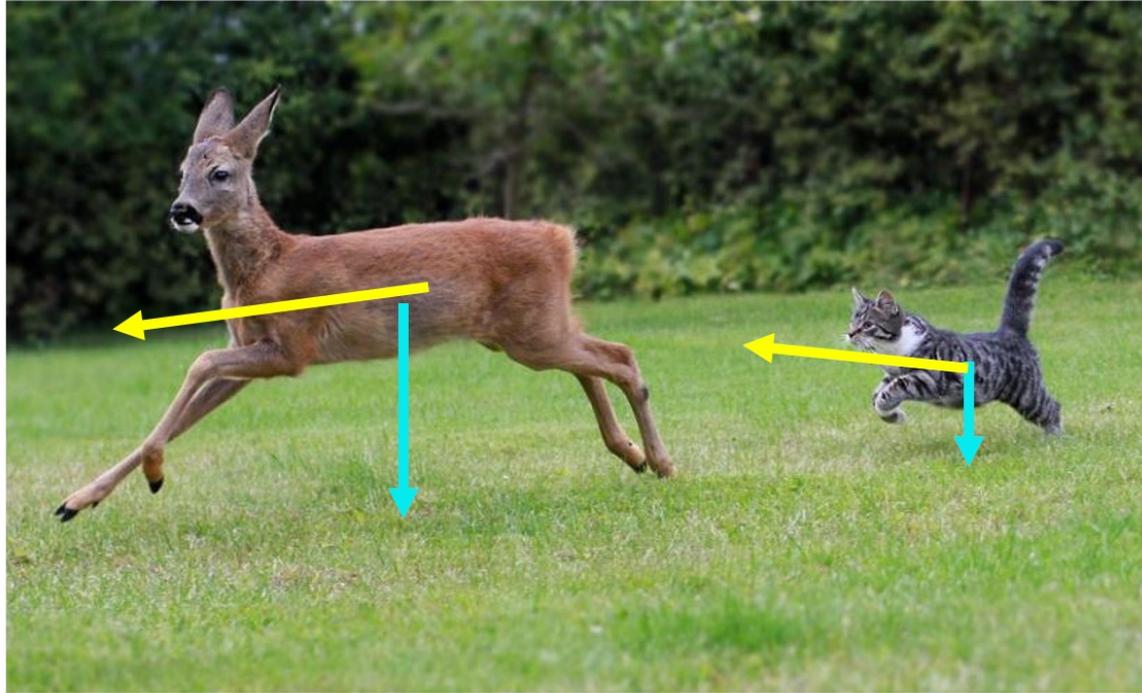
# What is Visual Recognition?

## Object segmentation



# What is Visual Recognition?

Physics / Intuition



↓ Gravity  
← Velocity

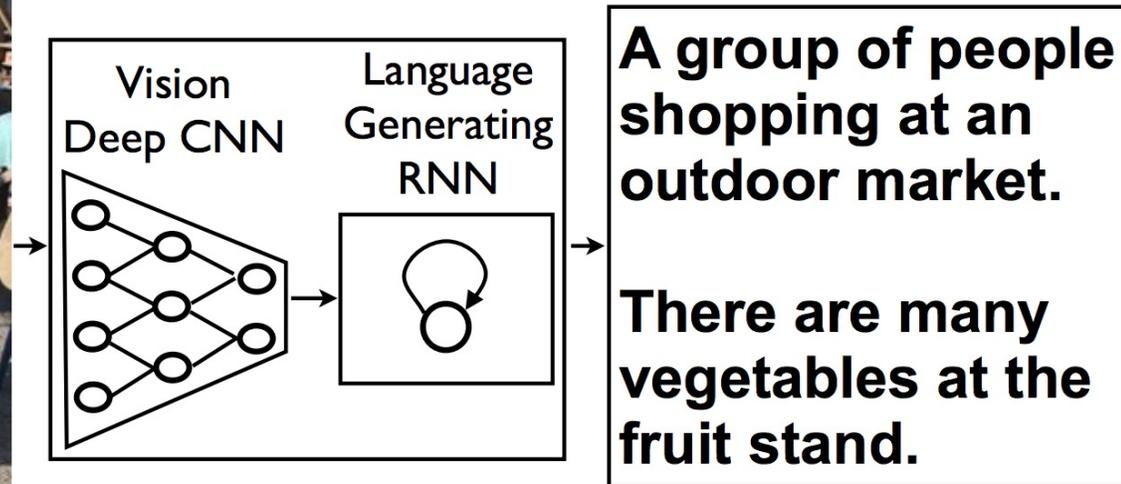
# Pushing the Limits of Visual Recognition

Reasoning about Language!



a cat is chasing a  
young deer

# Vision + Language: Applications (1)



Visual Captioning: Vinyals et al. 2015

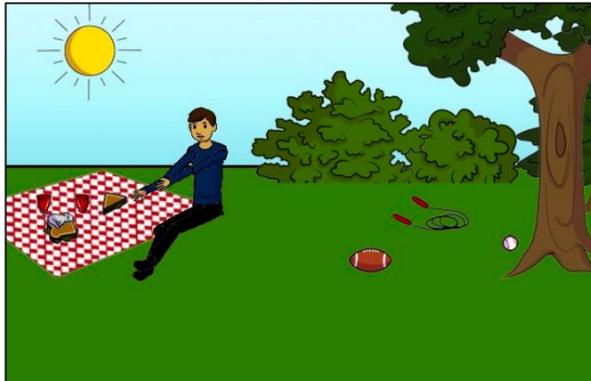
# Vision + Language: : Applications (2)



What color are her eyes?  
What is the mustache made of?



How many slices of pizza are there?  
Is this a vegetarian pizza?



Is this person expecting company?  
What is just under the tree?



Does it appear to be rainy?  
Does this person have 20/20 vision?

Visual Question Answering: Agrawal et al. 2015

# Vision + Language : Applications (3)

This bird has a yellow belly and tarsus, grey back, wings, and brown throat, nape with a black face



This bird is white with some black on its head and wings, and has a long orange beak



This flower has overlapping pink pointed petals surrounding a ring of short yellow filaments



Text to Images: Zhang et al. 2016

# Problem Overview (1): Visual Captioning

- Describe the content of an image or video with a natural language sentence.



A cat is sitting next to a pine tree, looking up.



A dog is playing piano with a girl.

# Applications of Visual Captioning

- Alt-text generation (from PowerPoint)
- Content-based image retrieval (CBIR)
- Helping the visually impaired
- Or just for fun!



Alt Text: A cat sitting on top of a grass covered field

a man is eating a hot dog in a crowd



A fun video running visual captioning model real-time made by Kyle McDonald. Source: <https://vimeo.com/146492001>

# Image Captioning with CNN-LSTM

- Problem Formulation

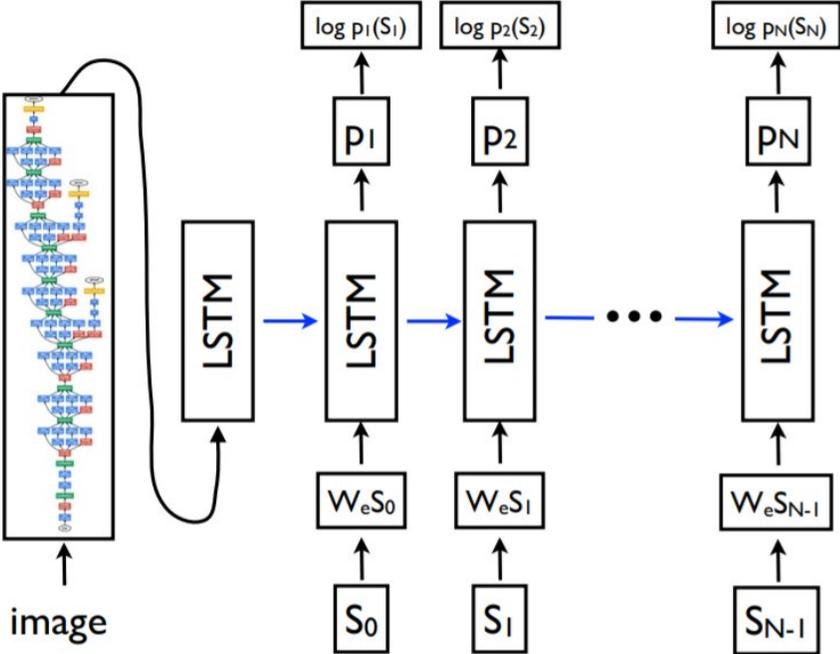
$$\theta^* = \arg \max_{\theta} \sum_{(I,S)} \log p(S|I; \theta)$$

$$\log p(S|I) = \sum_{t=0}^N \log p(S_t|I, S_0, \dots, S_{t-1})$$

- The Encoder-Decoder framework



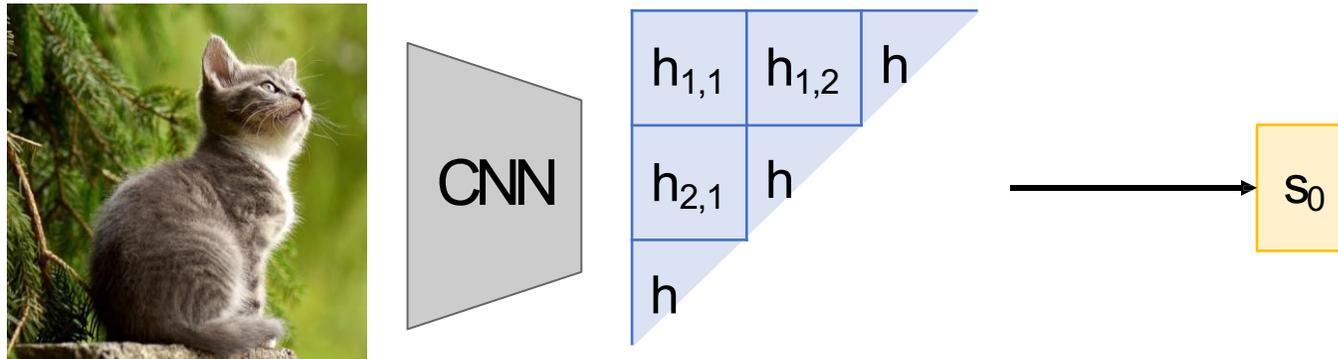
“Show and Tell”



# Image Captioning with Soft Attention

- Soft Attention – Dynamically attend to input content based on query.
- Basic elements: query –  $q$ , keys –  $K$ , and values –  $V$
- In our case, keys and values are usually identical. They come from the CNN activation map.
- Query  $q$  is determined by the global image feature or LSTM's hidden states.

# Image Captioning with Soft Attention



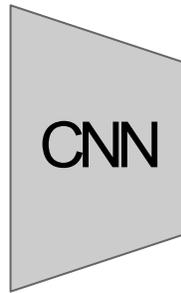
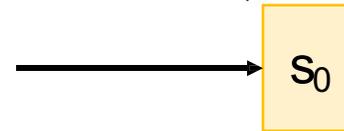
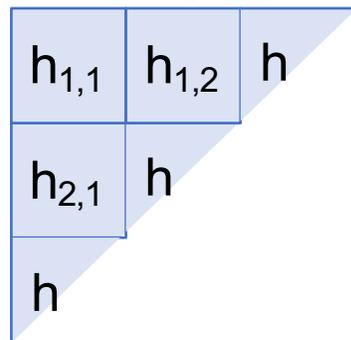
Use a CNN to compute a grid of features for an image

# Image Captioning with Soft Attention

$$e_{t,i,j} = f_{\text{att}}(s_{t-1}, h_{i,j})$$

Alignment scores

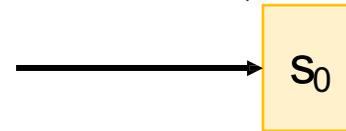
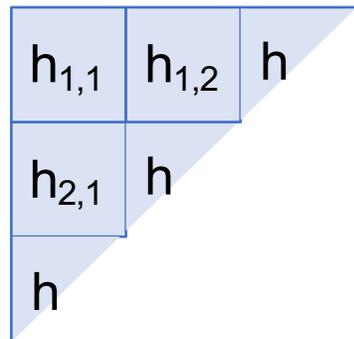
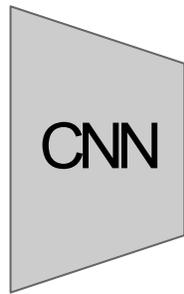
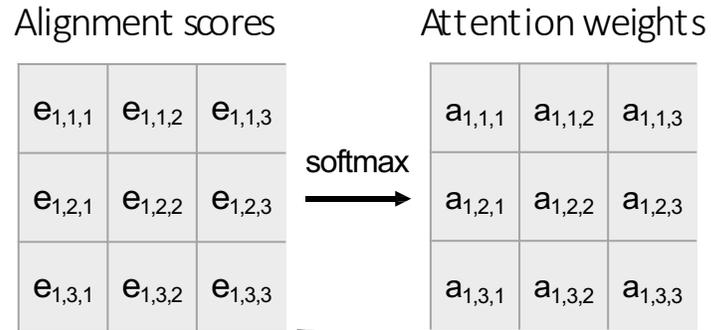
|             |             |             |
|-------------|-------------|-------------|
| $e_{1,1,1}$ | $e_{1,1,2}$ | $e_{1,1,3}$ |
| $e_{1,2,1}$ | $e_{1,2,2}$ | $e_{1,2,3}$ |
| $e_{1,3,1}$ | $e_{1,3,2}$ | $e_{1,3,3}$ |



Use a CNN to compute a grid of features for an image

# Image Captioning with Soft Attention

$$e_{t,i,j} = f_{\text{att}}(s_{t-1}, h_{i,j})$$
$$a_{t,:} = \text{softmax}(e_{t,:,:})$$



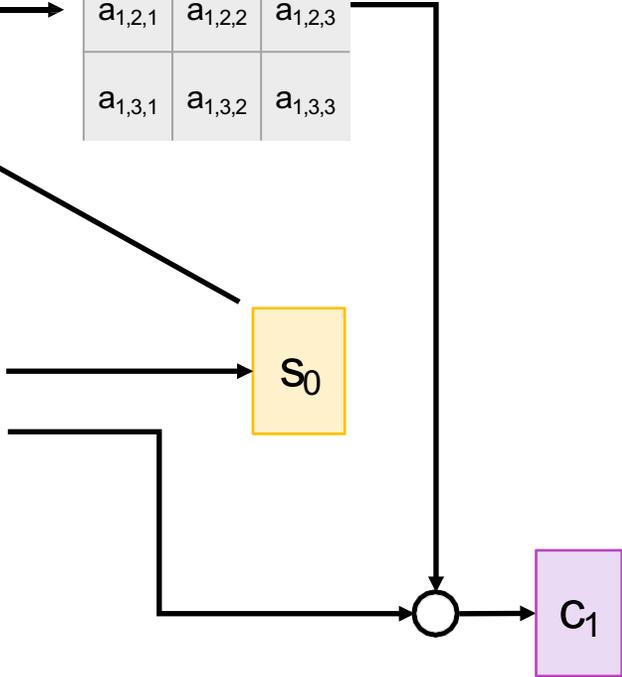
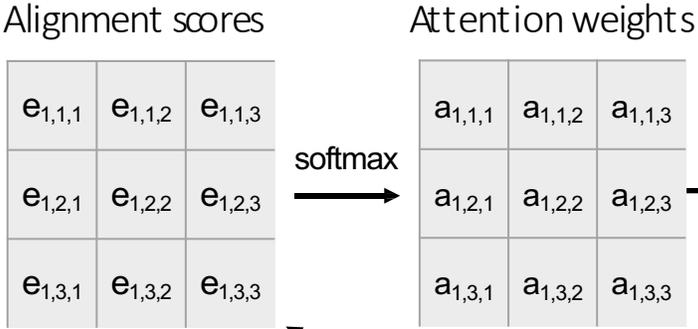
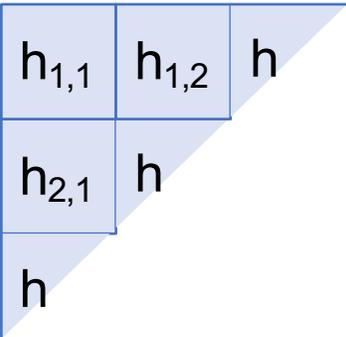
Use a CNN to compute a grid of features for an image

# Image Captioning with Soft Attention

$$e_{t,i,j} = f_{att}(s_{t-1}, h_{i,j})$$

$$a_{t,:} = \text{softmax}(e_{t,:})$$

$$c_t = \sum_{i,j} a_{t,i,j} h_{i,j}$$



Use a CNN to compute a grid of features for an image

# Image Captioning with Soft Attention

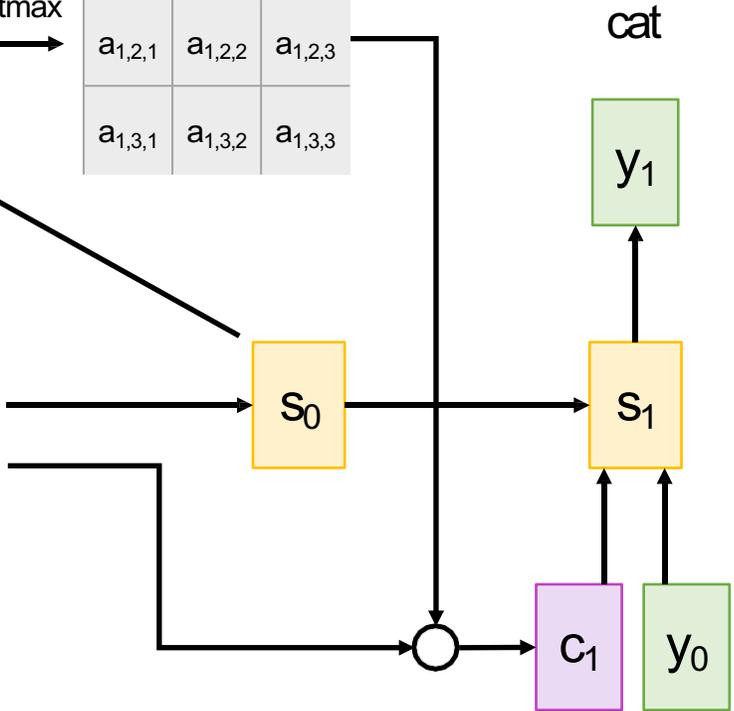
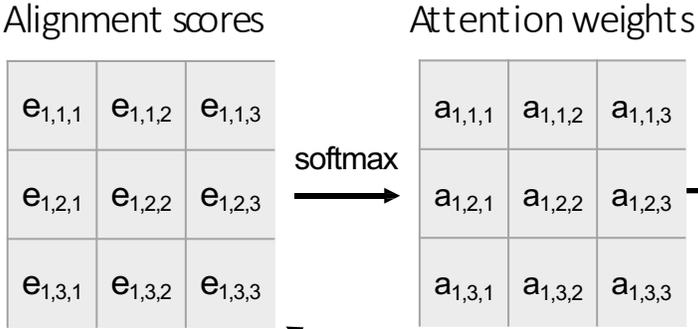
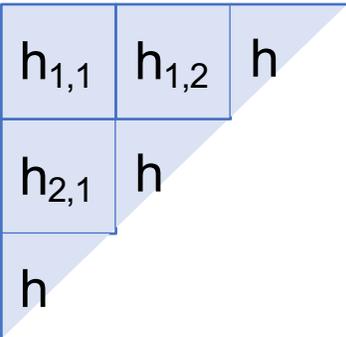
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$$c_t = \sum_{i,j} a_{t,i,j} h_{i,j}$$



CNN



[START]

Use a CNN to compute a grid of features for an image

# Image Captioning with Soft Attention

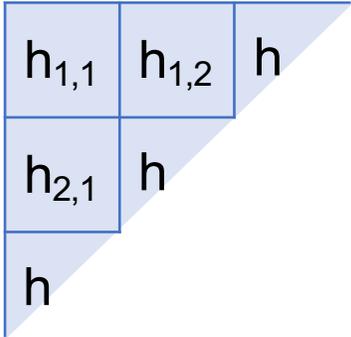
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$$a_{t,:} = \text{softmax}(e_{t,:})$$

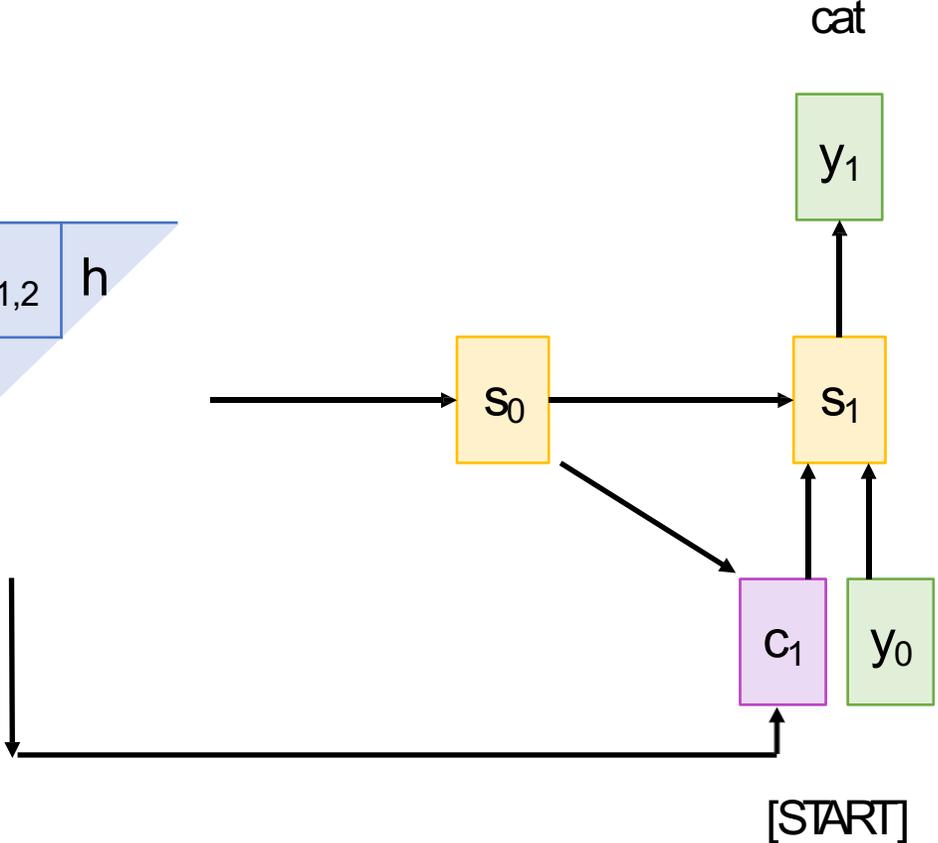
$$c_t = \sum_{i,j} a_{t,i,j} h_{i,j}$$



CNN



Use a CNN to compute a grid of features for an image



# Image Captioning with Soft Attention

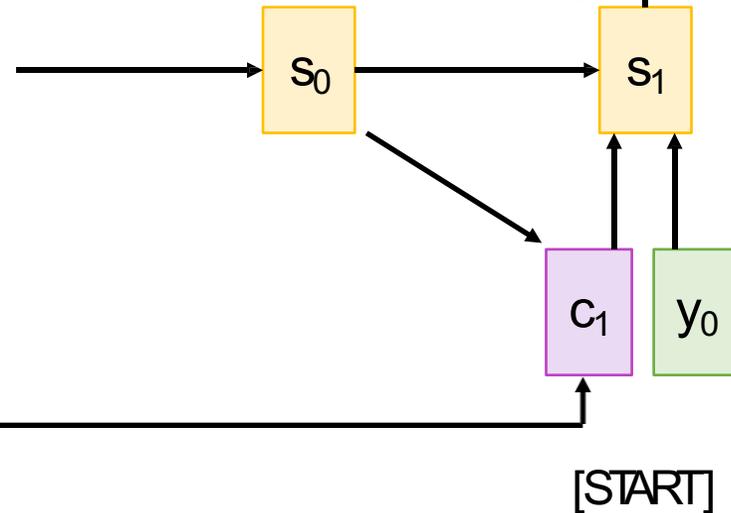
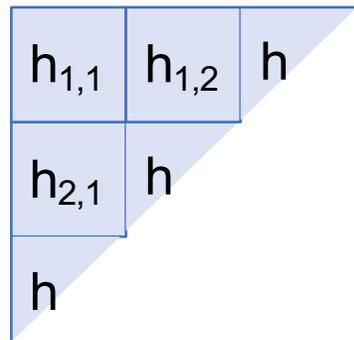
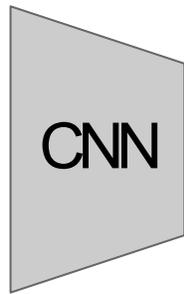
$$e_{t,i,j} = f_{\text{att}}(s_{t-1}, h_{i,j})$$

$$a_{t,:} = \text{softmax}(e_{t,:,:})$$

$$c_t = \sum_{i,j} a_{t,i,j} h_{i,j}$$

Alignment scores

|             |             |             |
|-------------|-------------|-------------|
| $e_{2,1,1}$ | $e_{2,1,2}$ | $e_{2,1,3}$ |
| $e_{2,2,1}$ | $e_{2,2,2}$ | $e_{2,2,3}$ |
| $e_{2,3,1}$ | $e_{2,3,2}$ | $e_{2,3,3}$ |



Use a CNN to compute a grid of features for an image

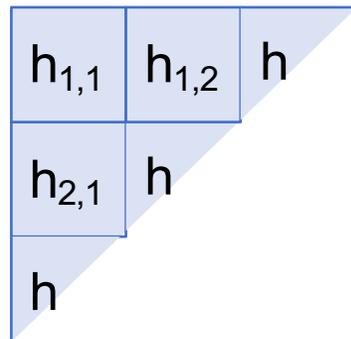
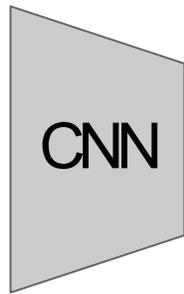
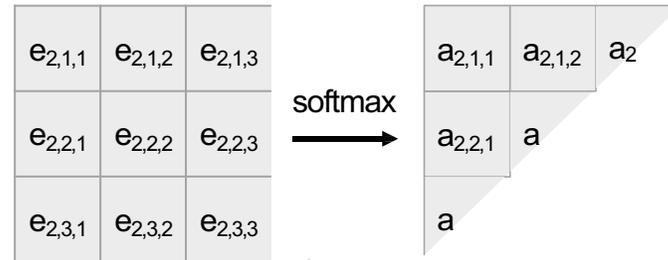
# Image Captioning with Soft Attention

$$e_{t,i,j} = f_{\text{att}}(s_{t-1}, h_{i,j})$$

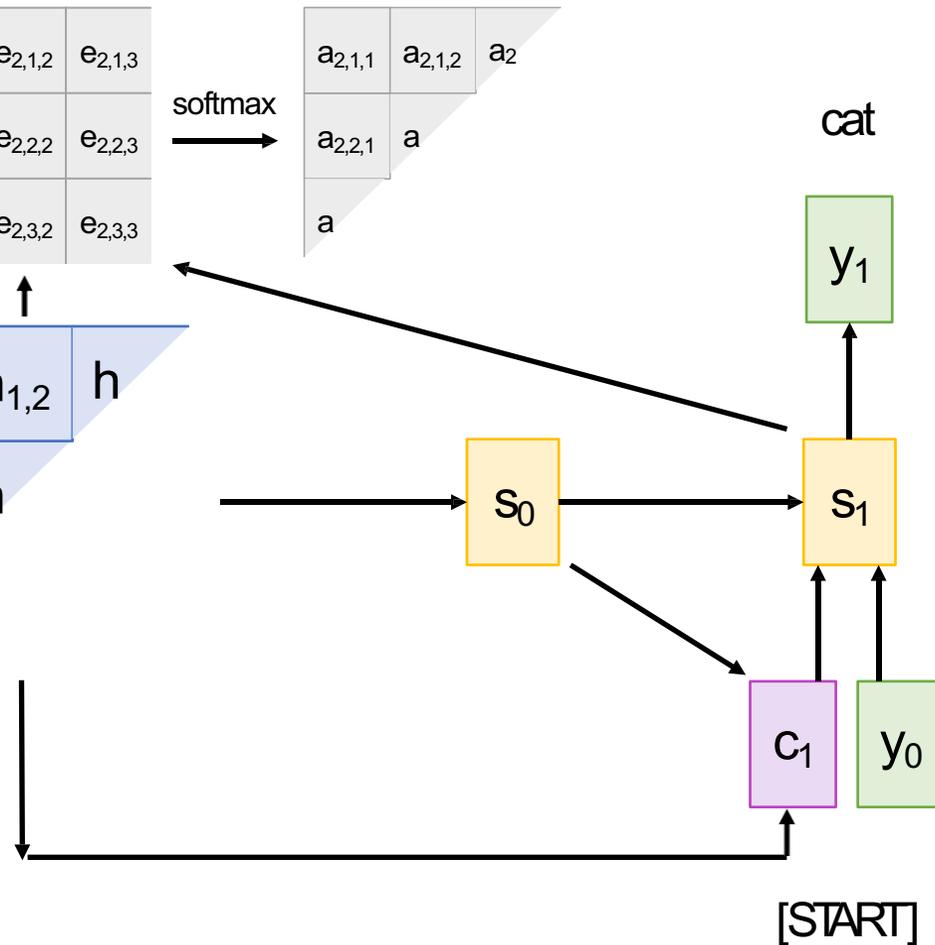
$$a_{t,:} = \text{softmax}(e_{t,:})$$

$$c_t = \sum_{i,j} a_{t,i,j} h_{i,j}$$

Alignment scores      Attention weights



Use a CNN to compute a grid of features for an image



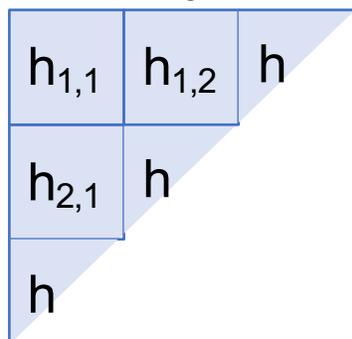
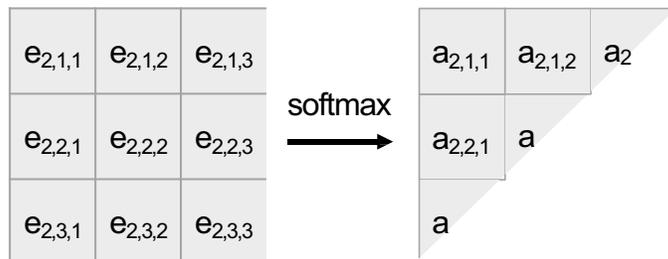
# Image Captioning with Soft Attention

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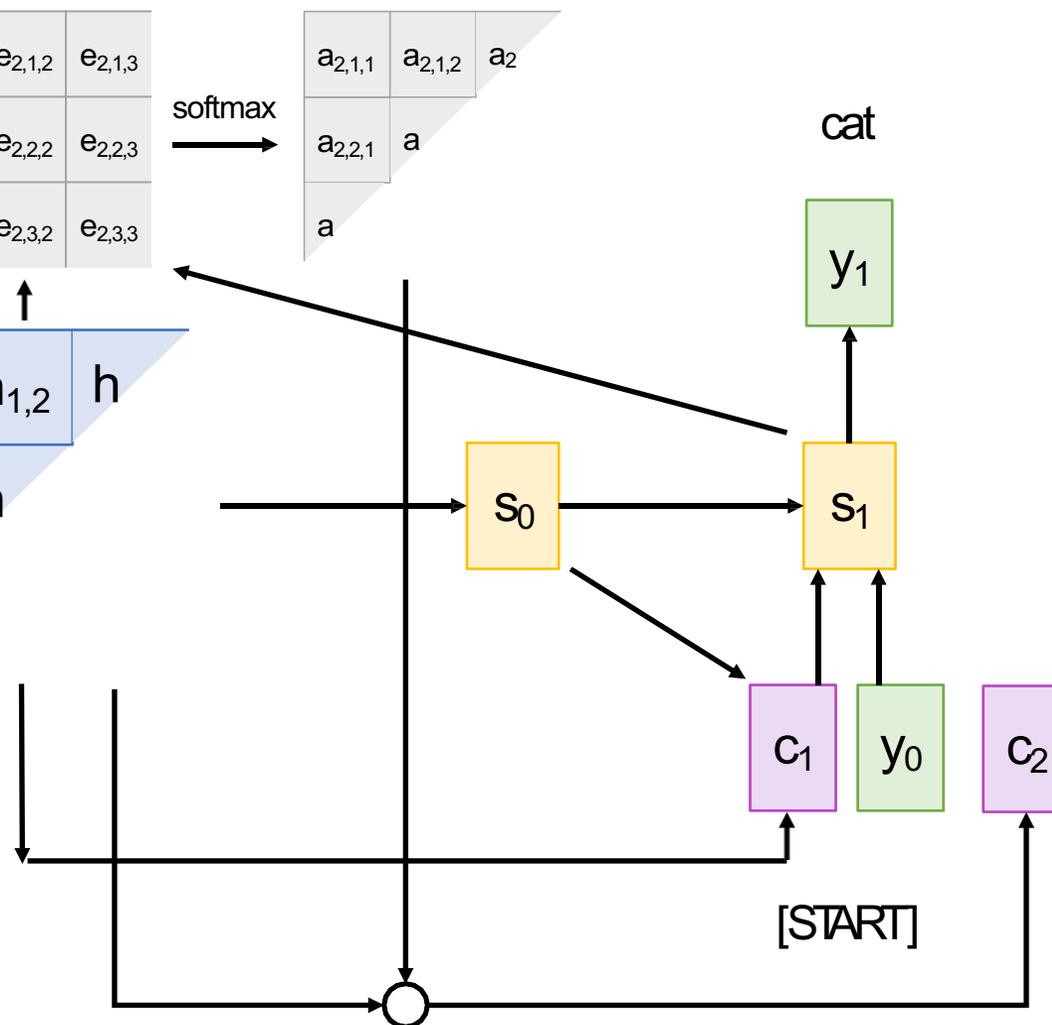
$$a_{t,:} = \text{softmax}(e_{t,:})$$

$$c_t = \sum_{i,j} a_{t,i,j} h_{i,j}$$

Alignment scores      Attention weights



Use a CNN to compute a grid of features for an image



# Image Captioning with Soft Attention

$$e_{t,i,j} = f_{\text{att}}(s_{t-1}, h_{i,j})$$

$$a_{t,:} = \text{softmax}(e_{t,:})$$

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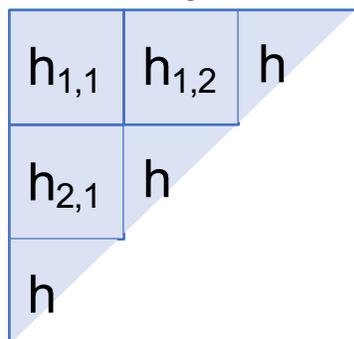
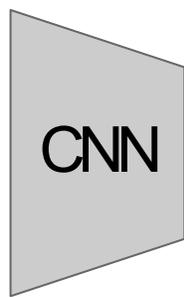
Alignment scores

|             |             |             |
|-------------|-------------|-------------|
| $e_{2,1,1}$ | $e_{2,1,2}$ | $e_{2,1,3}$ |
| $e_{2,2,1}$ | $e_{2,2,2}$ | $e_{2,2,3}$ |
| $e_{2,3,1}$ | $e_{2,3,2}$ | $e_{2,3,3}$ |

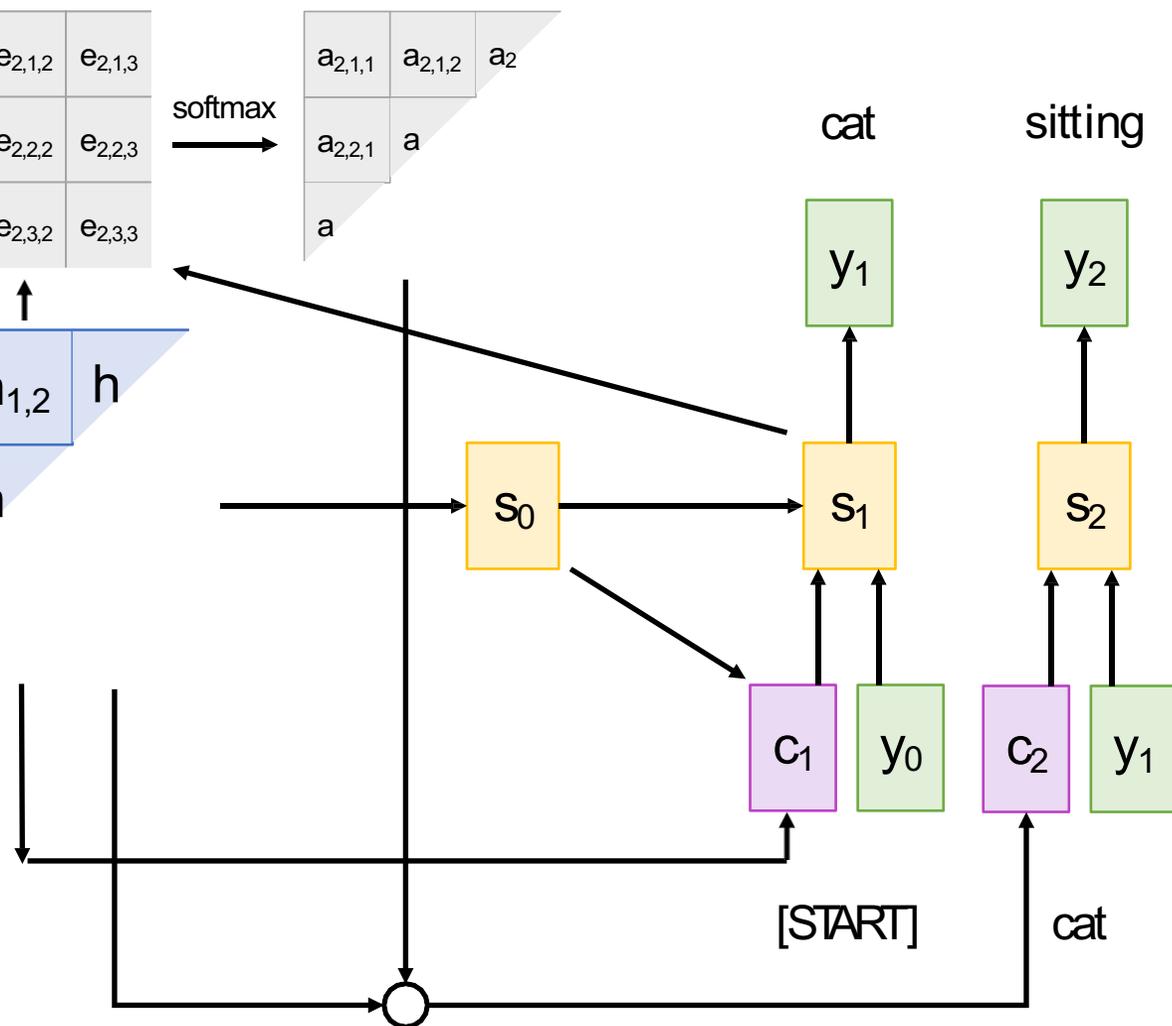
Attention weights

|             |             |             |
|-------------|-------------|-------------|
| $a_{2,1,1}$ | $a_{2,1,2}$ | $a_{2,1,3}$ |
| $a_{2,2,1}$ | $a_{2,2,2}$ | $a_{2,2,3}$ |
| $a_{2,3,1}$ | $a_{2,3,2}$ | $a_{2,3,3}$ |

softmax



Use a CNN to compute a grid of features for an image



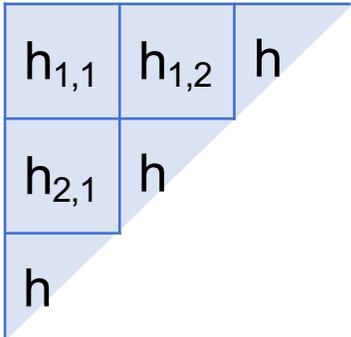
# Image Captioning with Soft Attention

$$e_{t,i,j} = f_{\text{att}}(s_{t-1}, h_{i,j})$$

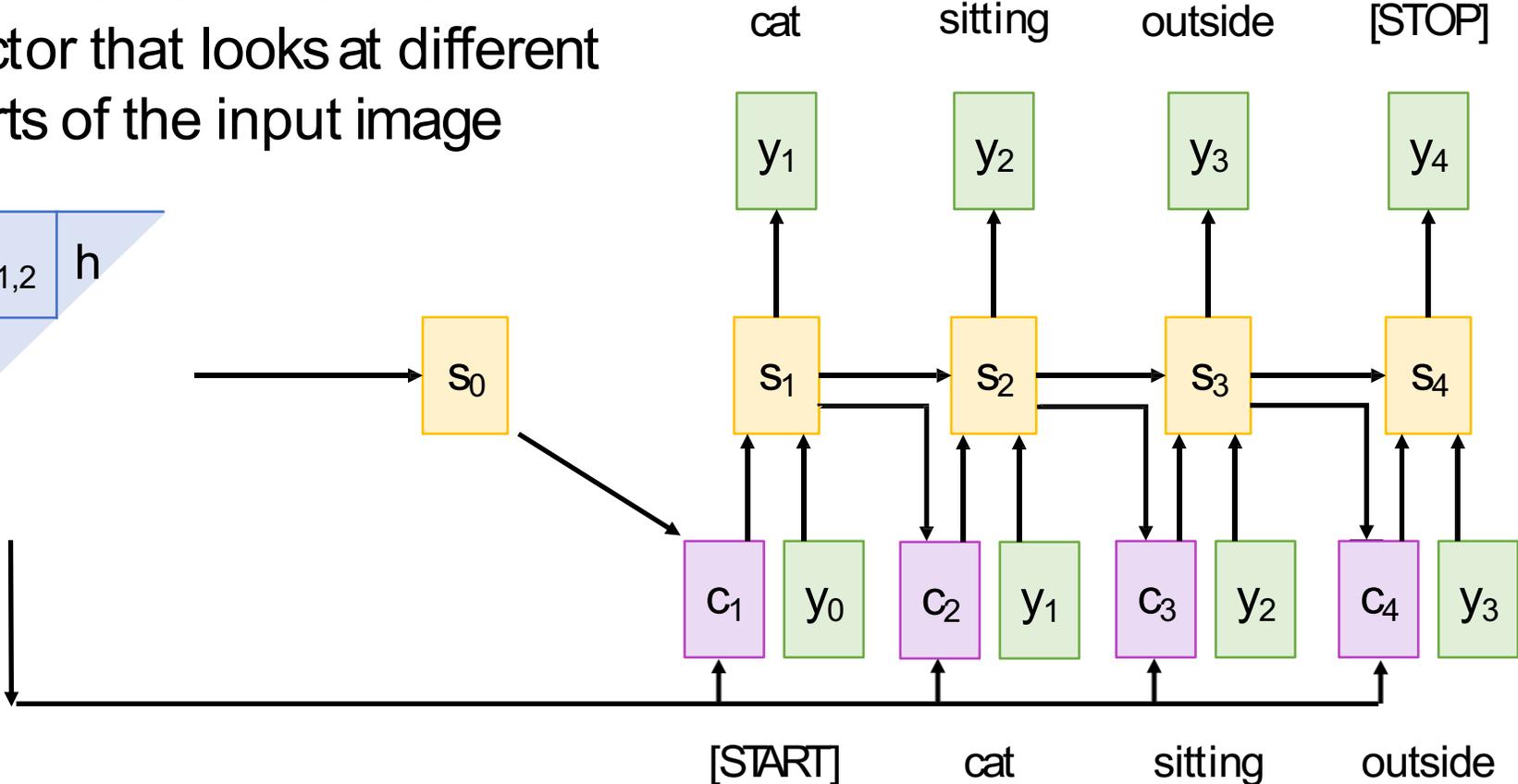
$$a_{t,:} = \text{softmax}(e_{t,:})$$

$$c_t = \sum_{i,j} a_{t,i,j} h_{i,j}$$

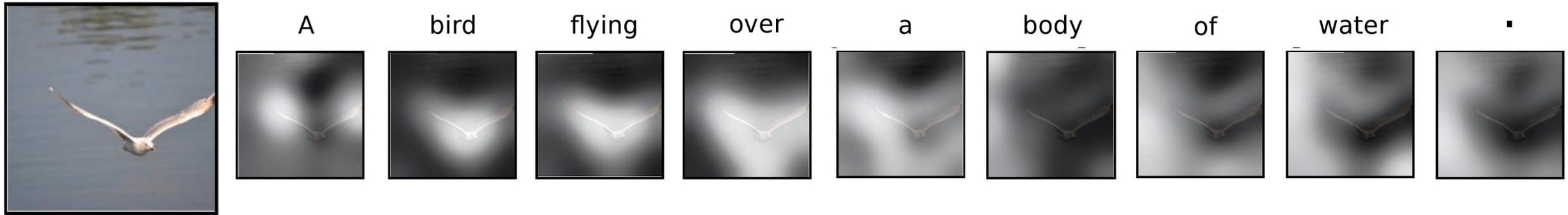
Each timestep of decoder uses a different context vector that looks at different parts of the input image



Use a CNN to compute a grid of features for an image

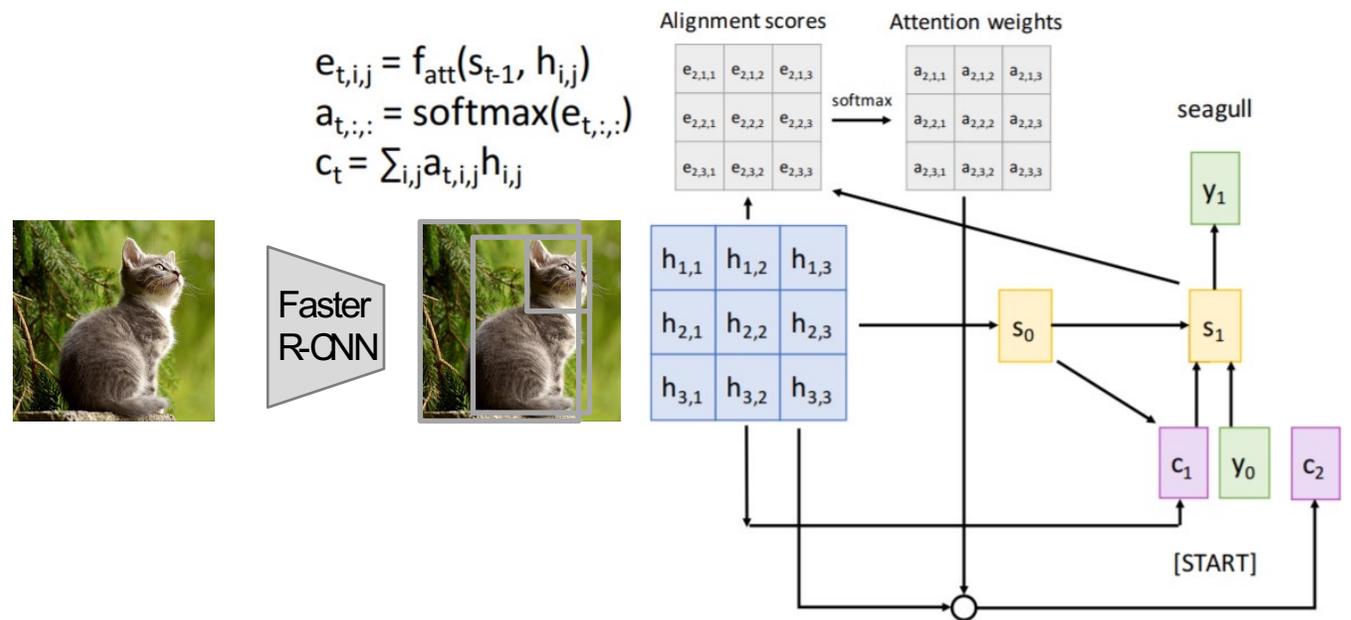


# Image Captioning with Soft Attention



# Image Captioning with Region Attention

- Variants of Soft Attention based on the feature input
  - Grid activation features (covered)
  - Region proposal features



# Image Captioning with Transformer

- Transformer performs sequence-to-sequence generation.
- Self-Attention – A type of soft attention that “attends to itself”.
- Self-Attention is a special case of Graph Neural Networks (GNNs) that has a fully-connected graph.
- Self-attention is sometimes used to model relationship between object regions, similar to GCNs.

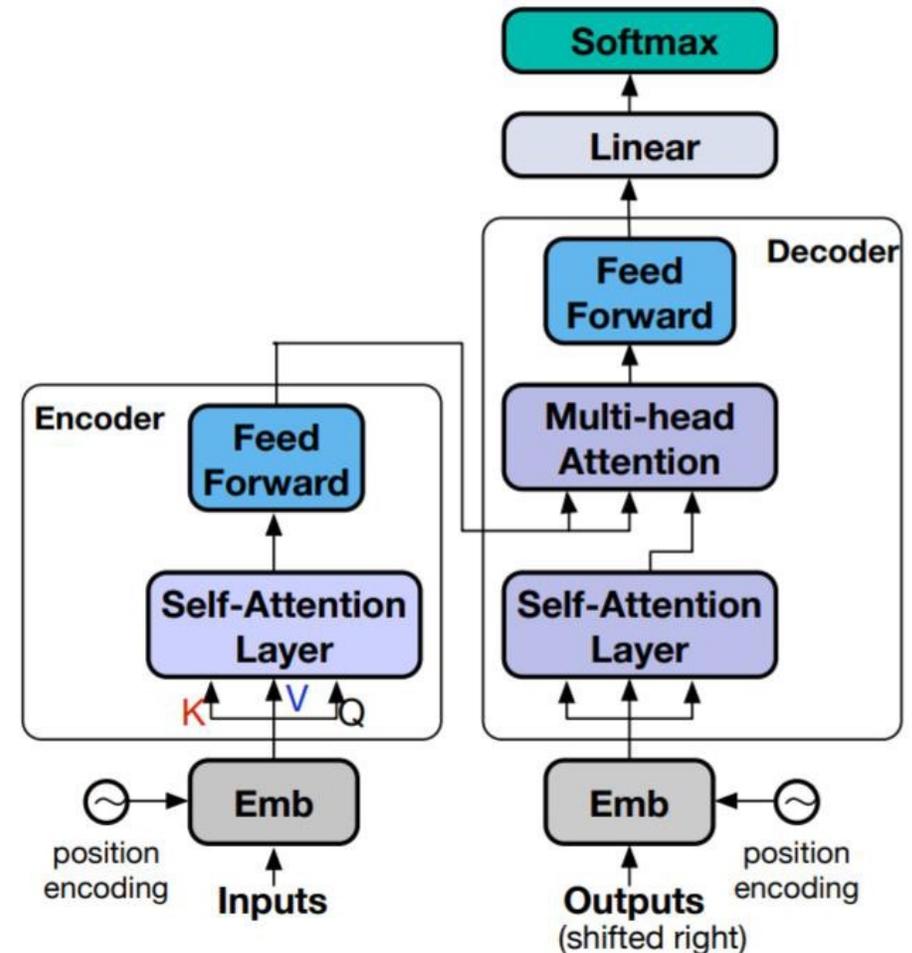
Vaswani et al. “Attention is all you need”, NIPS2017.

Yao et al. “Exploring visual relationship for image captioning”, ECCV 2018.

Further readings: <https://graphdeeplearning.github.io/post/transformers-are-gnns/>

# Image Captioning with Transformer

- Transformer is first adapted for captioning in Zhou et al.
- Others: Object Relation Transformer, Meshed-Memory Transformer



Zhou et al. "End-to-end dense video captioning with masked transformer", CVPR2018.

Herdade et al. "Image Captioning: Transforming Objects into Words", NeurIPS 2019.

Comia et al. "Meshed-Memory Transformer for Image Captioning", CVPR2020.

# Vision-Language Pre-training (VLP)

- Two-stage training strategy: **pre-training** and **fine-tuning**.
- **Pre-training** is performed on a large dataset. Usually with auto-generated captions. The training objective is *unsupervised*.
- **Fine-tuning** is task-specific *supervised* training on downstream tasks.
- All methods are based on BERT (a variant of Transformer).

# VideoBERT: A Joint Model for Video and Language Representation Learning

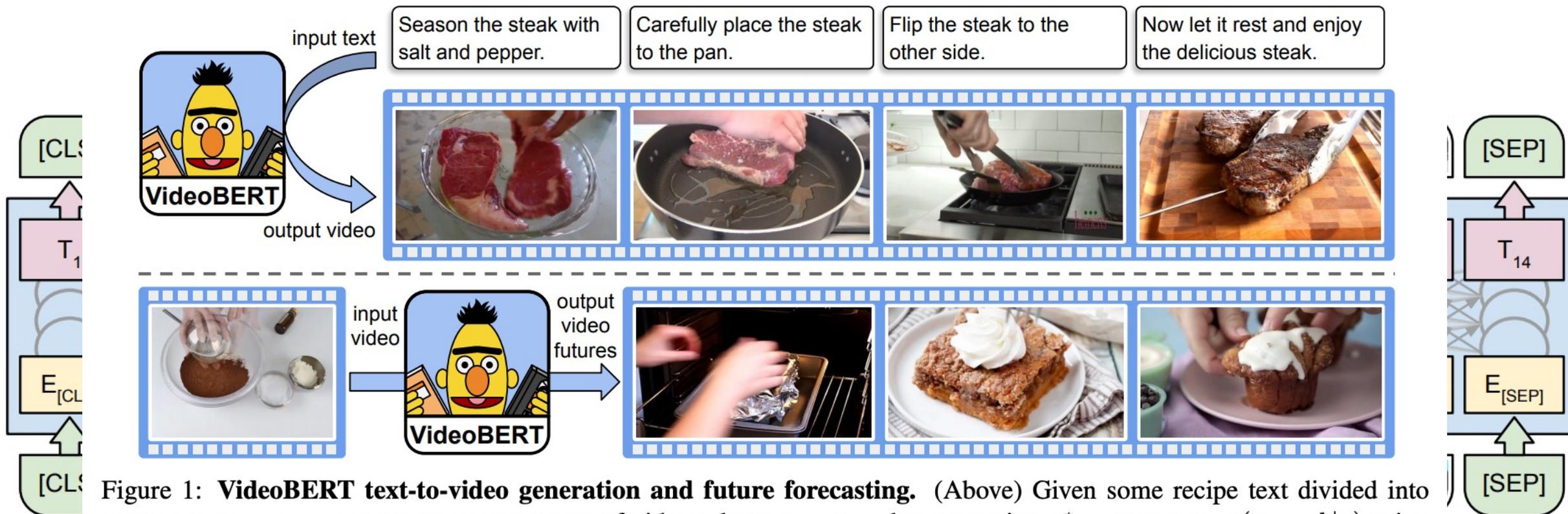


Figure 1: **VideoBERT text-to-video generation and future forecasting.** (Above) Given some recipe text divided into sentences,  $y = y_{1:T}$ , we generate a sequence of video tokens  $x = x_{1:T}$  by computing  $x_t^* = \arg \max_k p(x_t = k|y)$  using VideoBERT. (Below) Given a video token, we show the top three future tokens forecasted by VideoBERT at different time scales. In this case, VideoBERT predicts that a bowl of flour and cocoa powder may be baked in an oven, and may become a brownie or cupcake. We visualize video tokens using the images from the training set closest to centroids in feature space.

# Grounded Visual Description

- Essentially, visual description + object grounding or detection
- To achieve better result interpretability, we need grounding!
  - Image domain: Neural Baby Talk, etc.
  - Video domain: Grounded Video Description, etc.
- Requires special dataset that has both description and bounding box

# Single-Frame Annotation



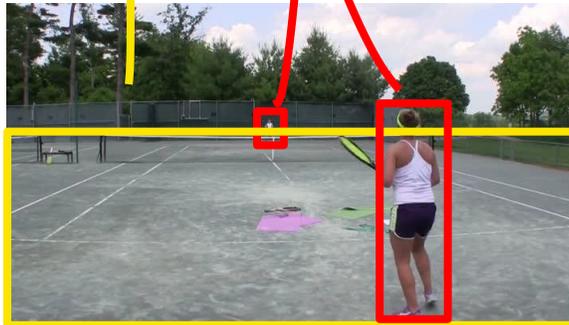
We see a man playing a saxophone  
in front of microphones.



# Multi-Frame Annotation

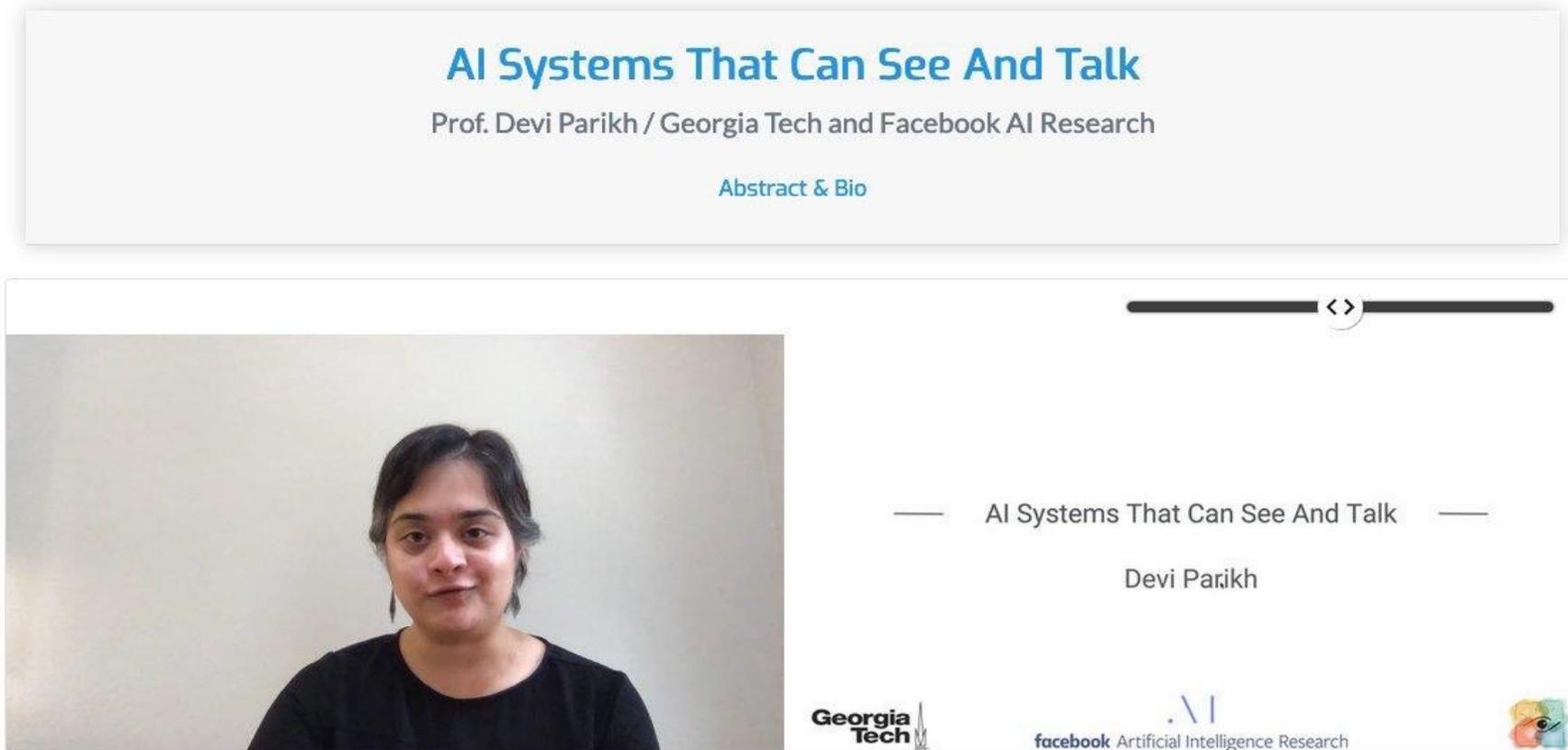


Two women are on a tennis court, showing the technique to posing and hitting the ball.



# Problem Overview (2): VQA and Visual Reasoning

- How to train a smart multi-modal AI system that can both see and talk?



The image shows a presentation slide with a video feed of Prof. Devi Parikh on the left. The slide content includes the title 'AI Systems That Can See And Talk', the presenter's name 'Devi Parikh', and logos for Georgia Tech, Facebook AI Research, and a colorful eye icon. A navigation bar at the top right features a double arrow icon.

**AI Systems That Can See And Talk**  
Prof. Devi Parikh / Georgia Tech and Facebook AI Research

[Abstract & Bio](#)

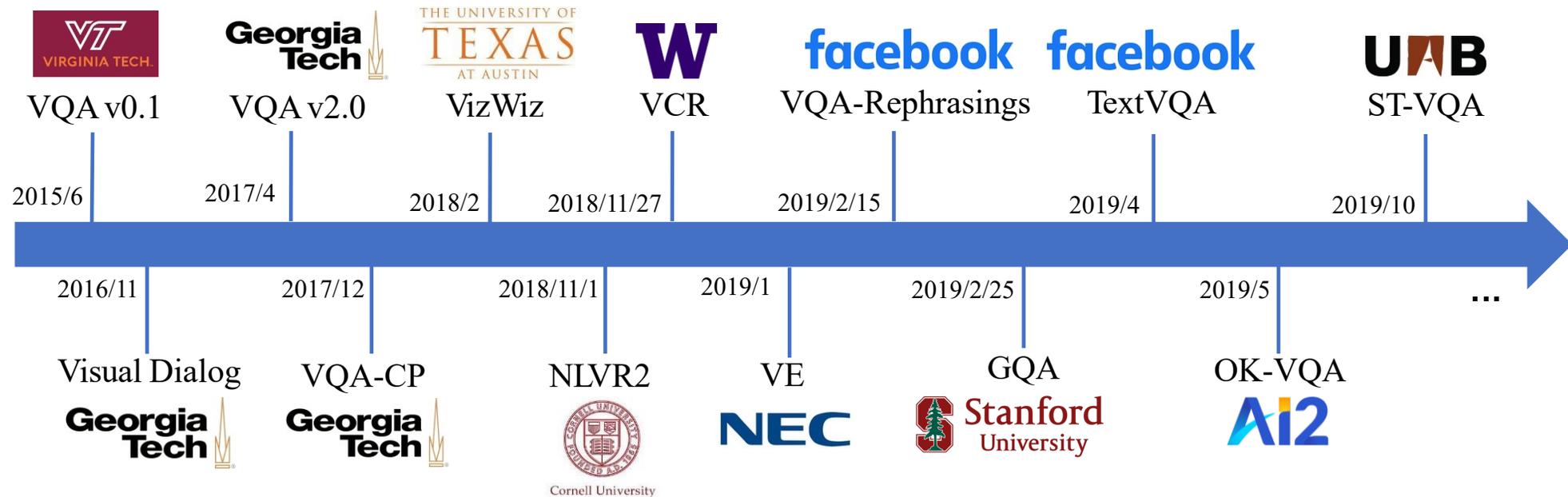
AI Systems That Can See And Talk

Devi Parikh

Georgia Tech | facebook Artificial Intelligence Research

# Problem Overview (2): VQA and Visual Reasoning

- Large-scale annotated datasets have driven tremendous progress in this field



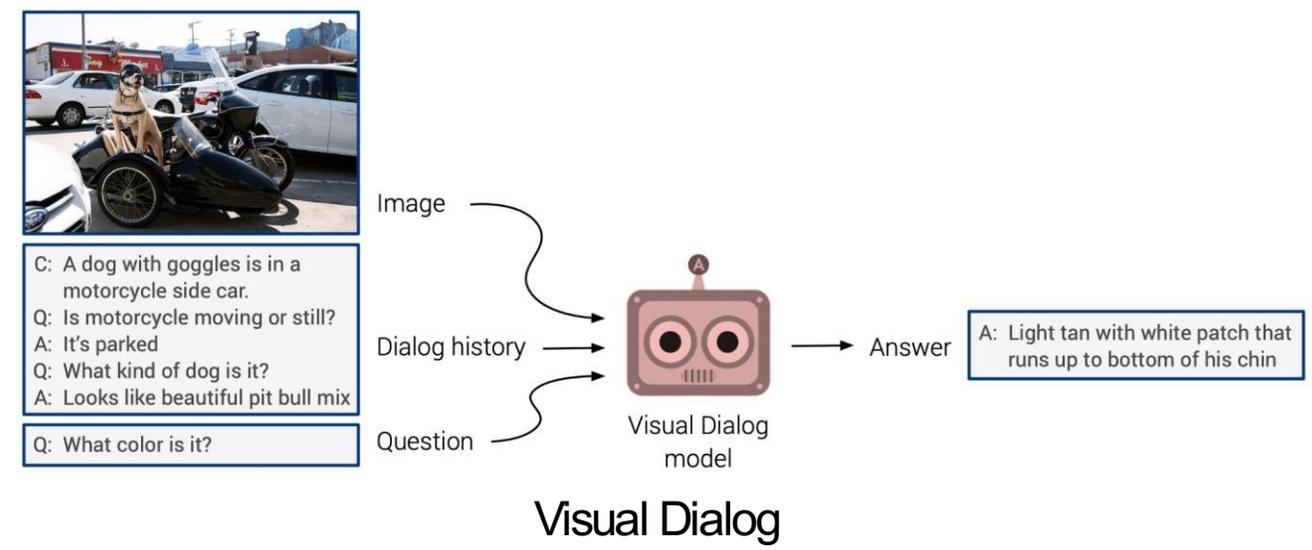
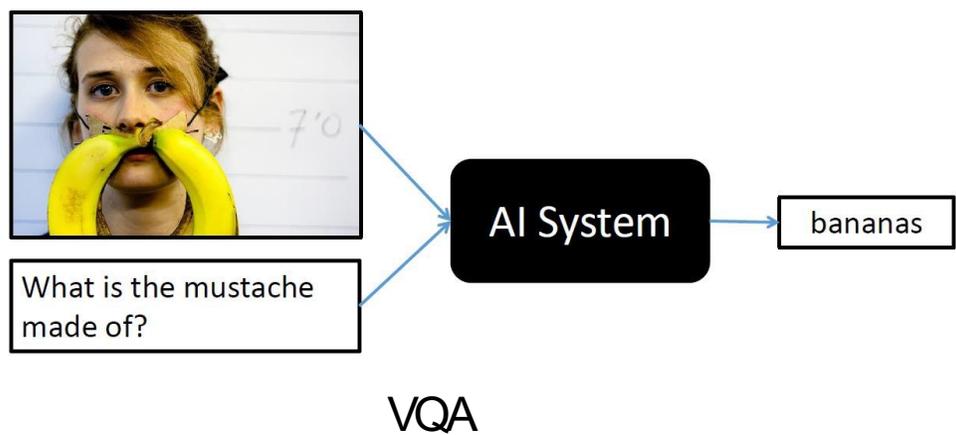
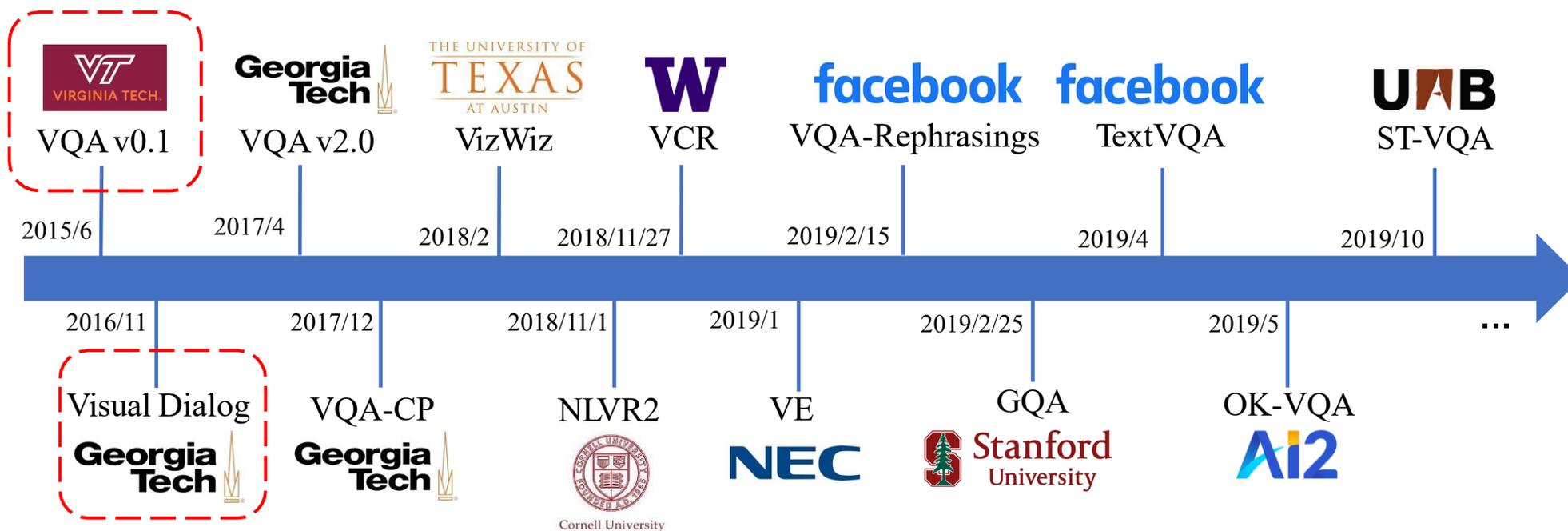
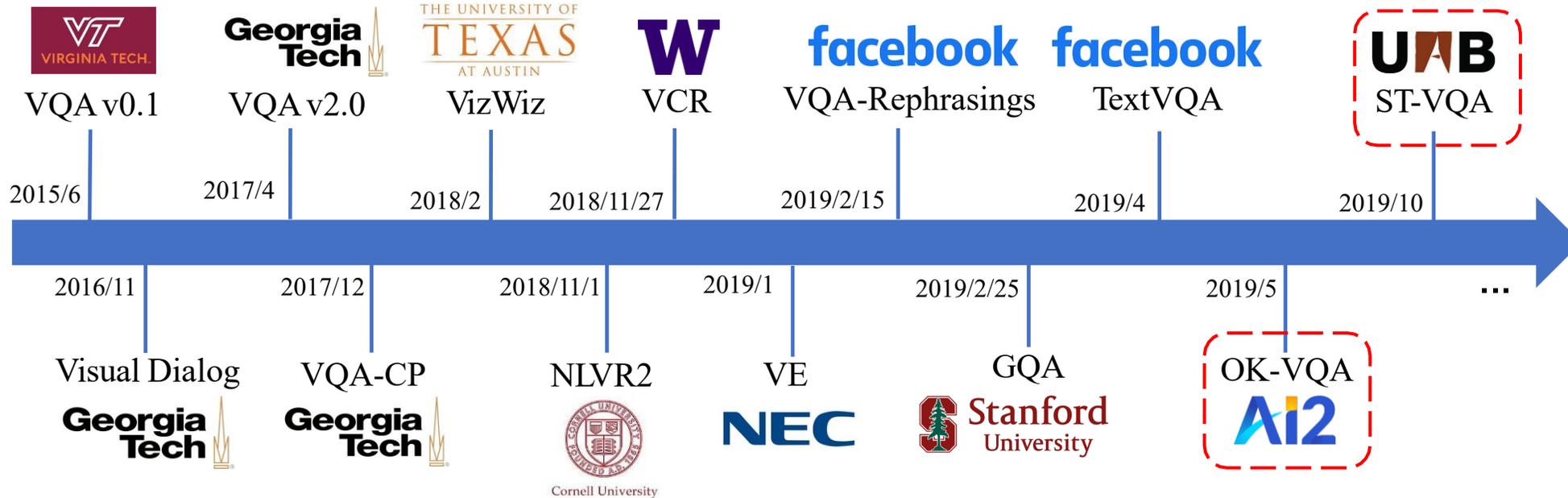


Image credit: <https://visualqa.org/>, <https://visualdialog.org/>

1 VQA: Visual Question Answering, ICCV 2015  
 2 Visual Dialog, CVPR 2017



Q: Which American president is associated with the stuffed animal seen here?

A: Teddy Roosevelt

#### Outside Knowledge

Another lasting, popular legacy of Roosevelt is the stuffed toy bears—teddy bears—named after him following an incident on a hunting trip in Mississippi in 1902.

Developed apparently simultaneously by toymakers ... and named after President Theodore "Teddy" Roosevelt, the teddy bear became an iconic children's toy, celebrated in story, song, and film.

At the same time in the USA, Morris Michtom created the first teddy bear, after being inspired by a drawing of Theodore "Teddy" Roosevelt with a bear cub.

OK-VQA



Q: What is the price of the bananas per kg?

A: \$11.98



Q: What does the red sign say?

A: Stop

Scene Text VQA

- 1 OK-VQA: A Visual Question Answering Benchmark Requiring External Knowledge, CVPR 2019
- 2 Scene Text Visual Question Answering, ICCV 2019

# Beyond VQA: Visual Grounding

- Referring Expression Comprehension: RefCOCO(+/g)
  - ReferIt Game: Referring to Objects in Photographs of Natural Scenes
- Flickr30k Entities



- A man with pierced ears is wearing glasses and an orange hat.
- A man with glasses is wearing a beer can crocheted hat.
- A man with gauges and glasses is wearing a Blitz hat.
- A man in an orange hat starring at something.
- A man wears an orange hat and glasses.

# Beyond VQA: Visual Grounding

- PhraseCut: Language-based image segmentation

short deer



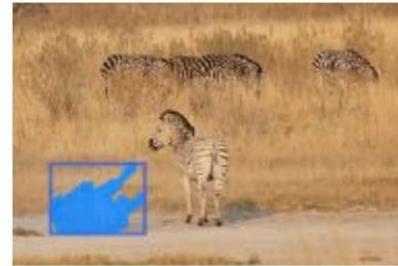
walking people



wipers on trains



zebra lying on savanna



black shirt



hatchback car



mark on chicken



glass bottles



blonde hair

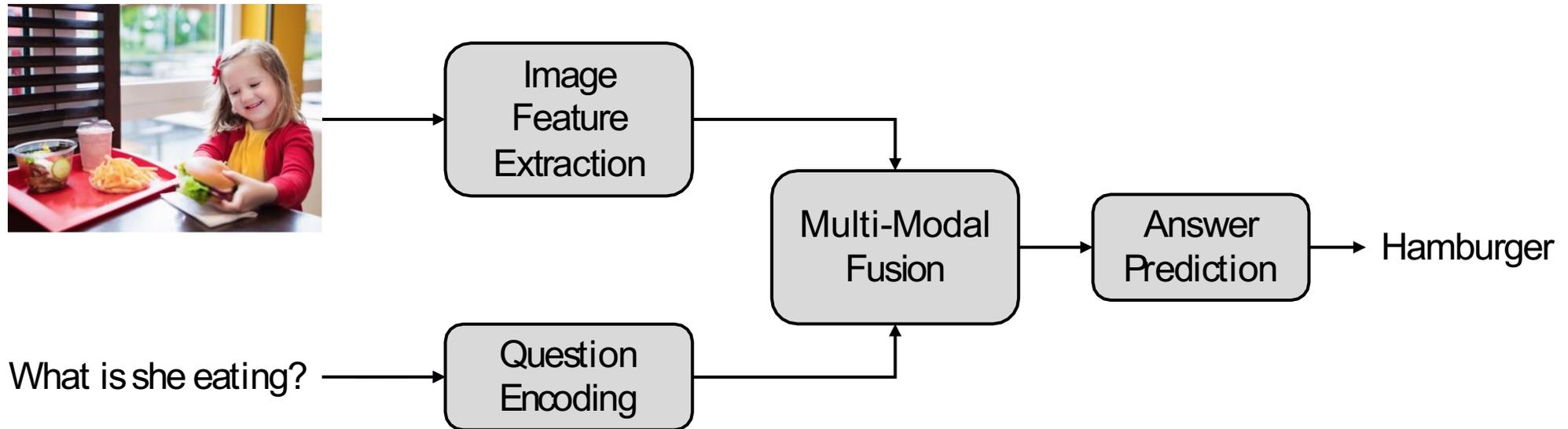


pedestrian crosswalk



# Approach Overview

- How a typical system looks like

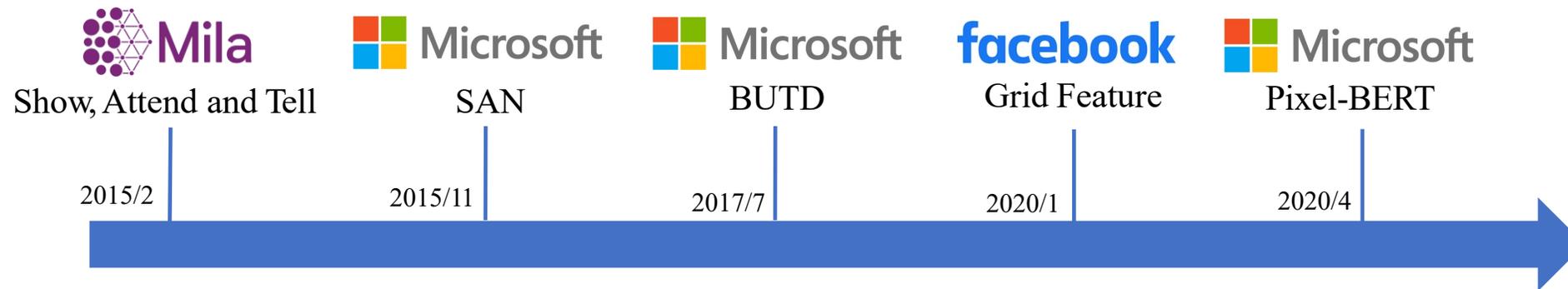


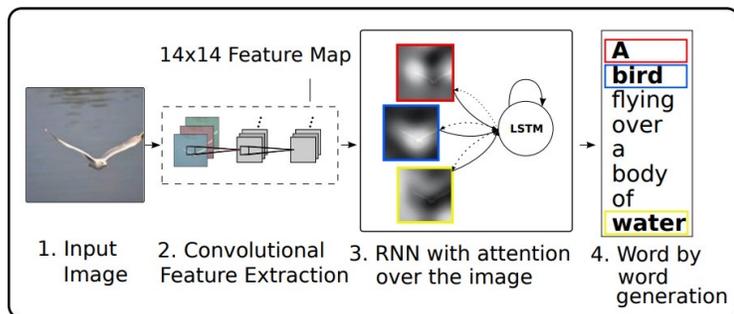
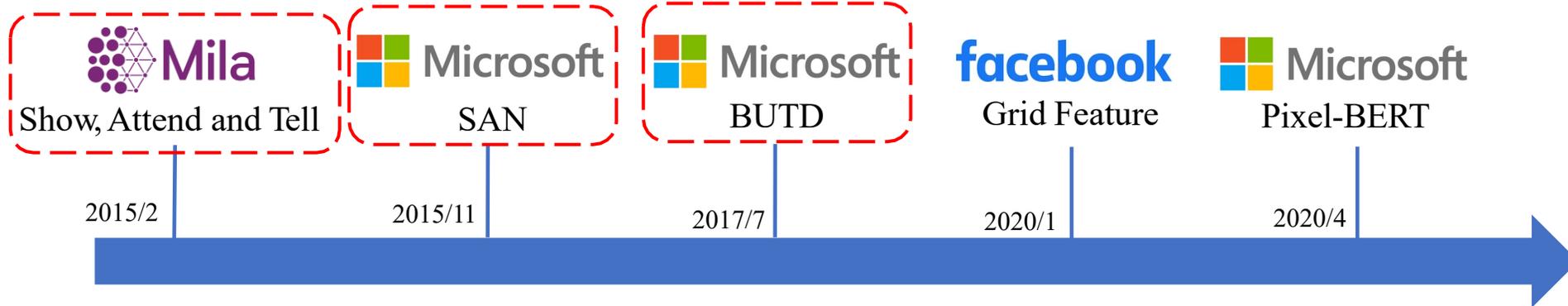
# Research Challenges & Opportunities

- Better image feature preparation
- Enhanced multimodal fusion
  - Bilinear pooling: how to fuse two vectors into one
  - Multimodal alignment: *cross-modal* attention
  - Incorporation of object relations: *intra-modal* self-attention, graph attention
  - Multi-step reasoning
- Neural module networks for compositional reasoning
- Robust VQA
- Multimodal pre-training

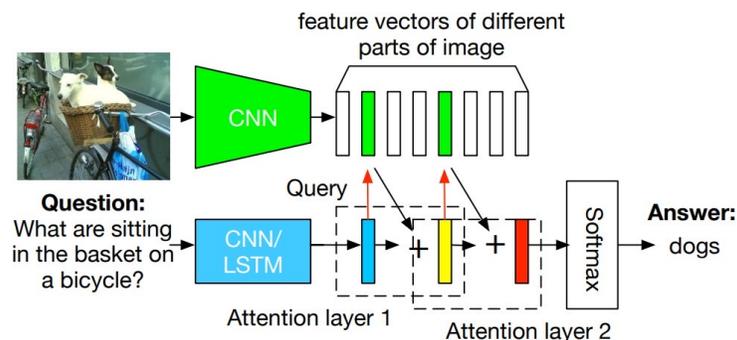
# Better Image Feature Preparation

- From *grid* features to *region* features, and to *grid* features again

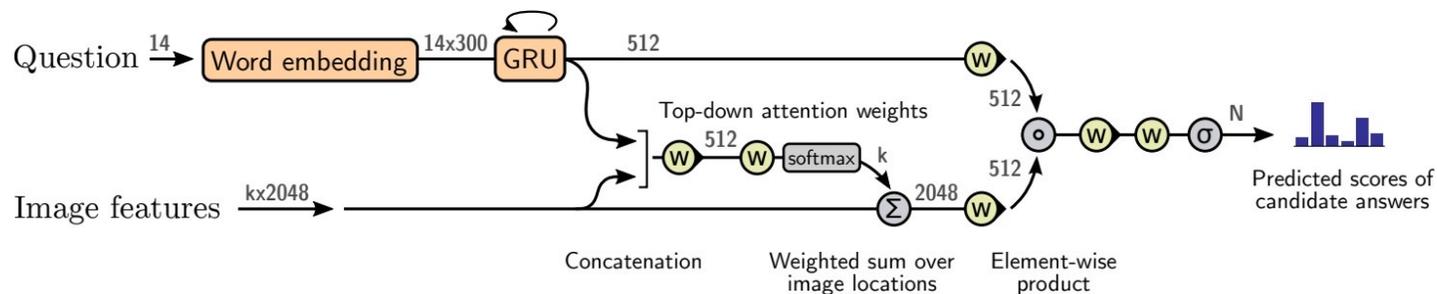




Show, Attend and Tell



Stacked Attention Network



2017 VQA Challenge Winner

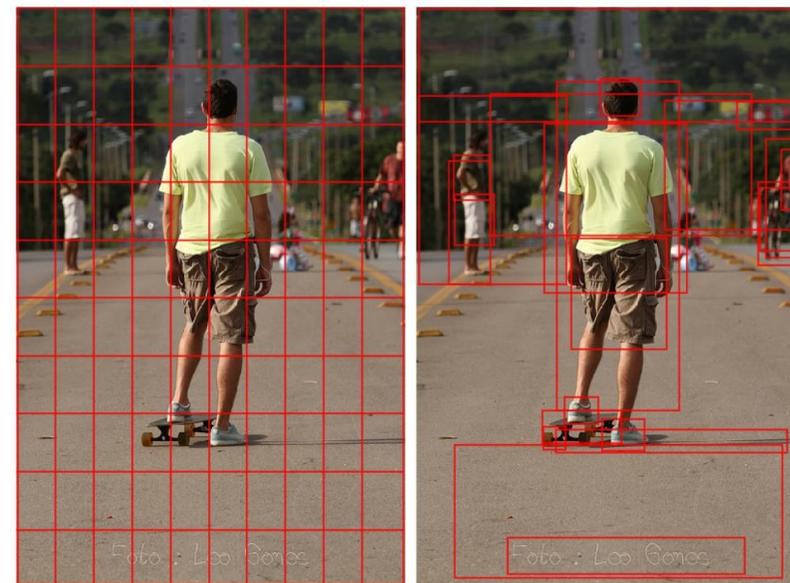


Figure 1. Typically, attention models operate on CNN features corresponding to a uniform grid of equally-sized image regions (left). Our approach enables attention to be calculated at the level of objects and other salient image regions (right).

- 1 Show, Attend and Tell: Neural Image Caption Generation with Visual Attention, ICML 2015
- 2 Stacked Attention Networks for Image Question Answering, CVPR 2016
- 3 Bottom-Up and Top-Down Attention for Image Captioning and Visual Question Answering, CVPR 2018

 **Mila**  
Show, Attend and Tell

2015/2

 **Microsoft**  
SAN

2015/11

 **Microsoft**  
BUTD

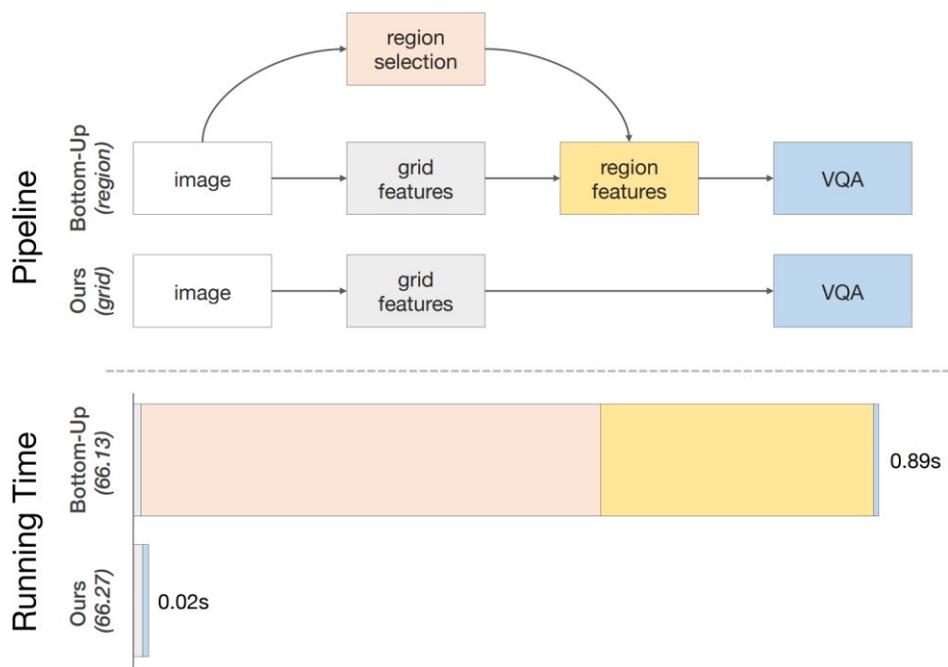
2017/7

 **facebook**  
Grid Feature

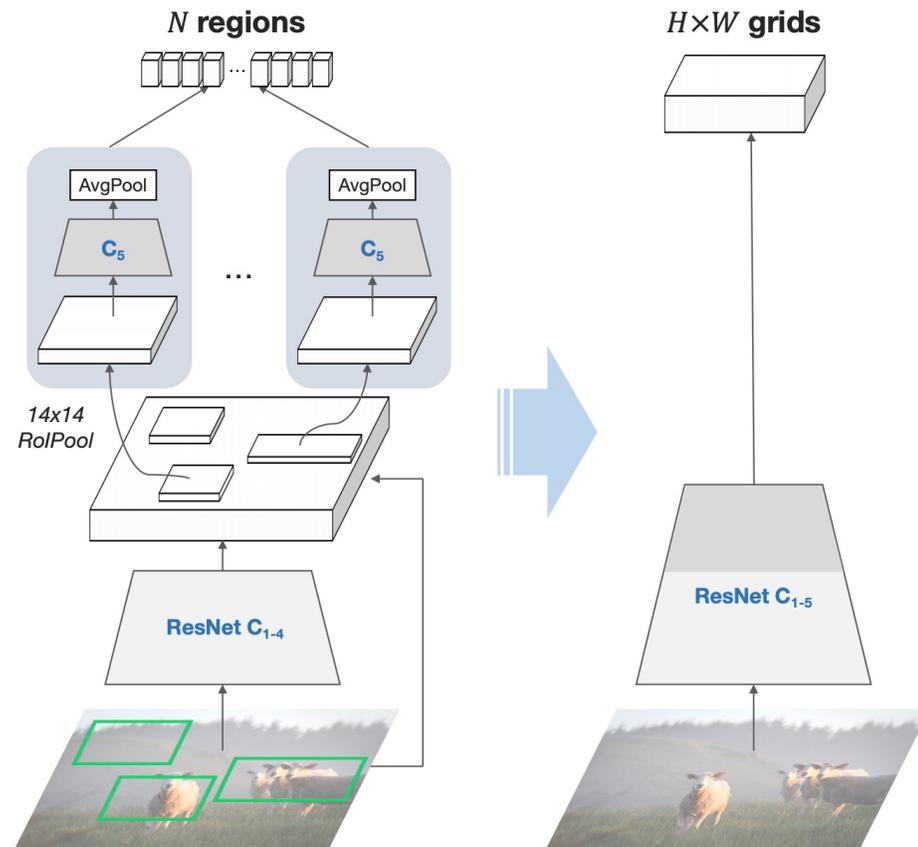
2020/1

 **Microsoft**  
Pixel-BERT

2020/4



**In Defense of Grid Features for VQA**



 **Mila**  
Show, Attend and Tell

2015/2

 **Microsoft**

SAN

2015/11

 **Microsoft**

BUTD

2017/7

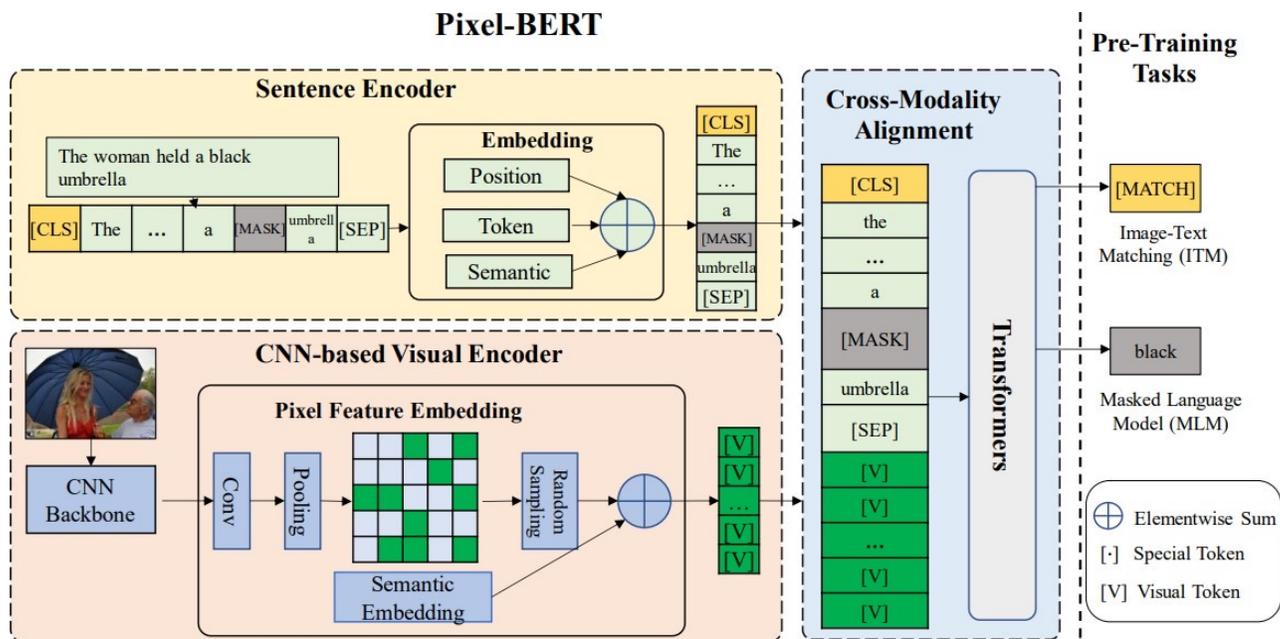
**facebook**

Grid Feature

2020/1

 **Microsoft**  
Pixel-BERT

2020/4



| Model             | test-dev     | test-std     |
|-------------------|--------------|--------------|
| MUTAN[5]          | 60.17        | -            |
| BUTD[2]           | 65.32        | 65.67        |
| ViLBERT[21]       | 70.55        | 70.92        |
| VisualBERT[19]    | 70.80        | 71.00        |
| VLBERT[29]        | 71.79        | 72.22        |
| LXMERT[33]        | 72.42        | 72.54        |
| UNITER[6]         | 72.27        | 72.46        |
| Pixel-BERT (r50)  | 71.35        | 71.42        |
| Pixel-BERT (x152) | <b>74.45</b> | <b>74.55</b> |

**Table 2.** Evaluation of Pixel-BERT with other methods on VQA.

# Bilinear Pooling

- Instead of simple concatenation and element-wise product for fusion, bilinear pooling methods have been studied
- Bilinear pooling and attention mechanism can be enhanced with each other





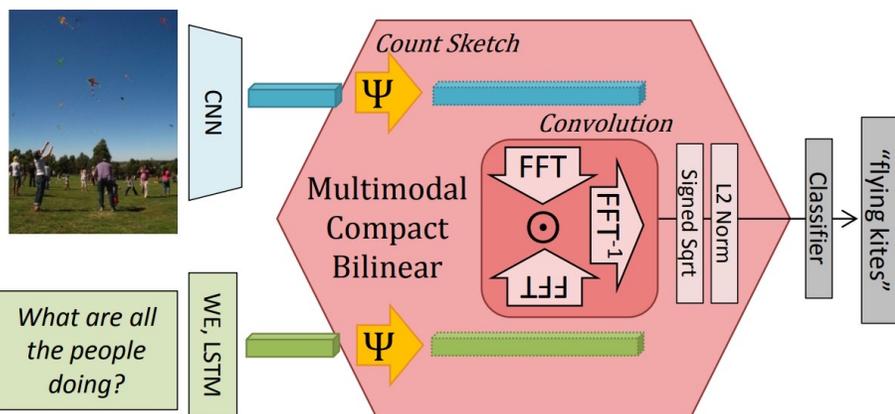
2016/6

2016/10

2017/5

2017/8

2019/1



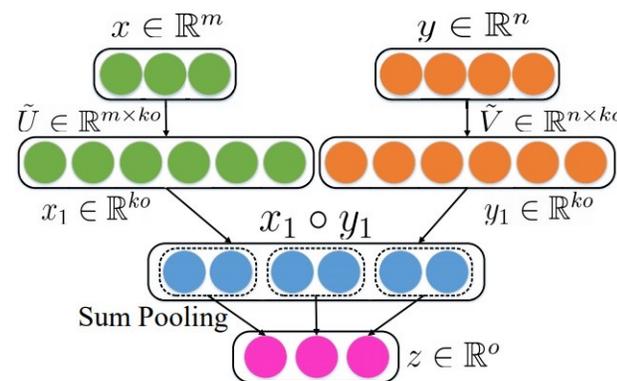
### Multimodal Compact Bilinear Pooling

*2016 VQA Challenge Winner*

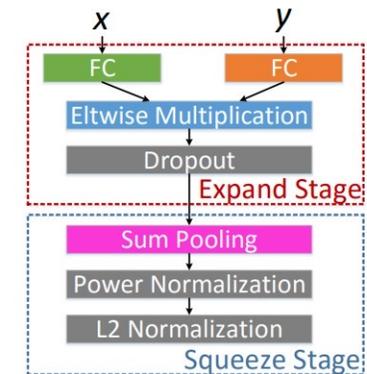
However, the feature after FFT is very high dimensional.

$$\mathbf{f} = \mathbf{P}^T (\mathbf{U}^T \mathbf{x} \circ \mathbf{V}^T \mathbf{y}) + \mathbf{b}$$

### Multimodal Low-rank Bilinear Pooling



(a) Multi-modal Factorized Bilinear Pooling

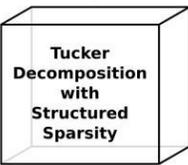


(b) MFB module

- 1 Multimodal Compact Bilinear Pooling for Visual Question Answering and Visual Grounding, EMNLP 2016
- 2 Hadamard Product for Low-rank Bilinear Pooling, ICLR 2017
- 3 Multi-modal Factorized Bilinear Pooling with Co-Attention Learning for Visual Question Answering, ICCV 2017

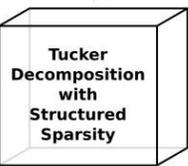


What is sitting on the desk in front of the boys?



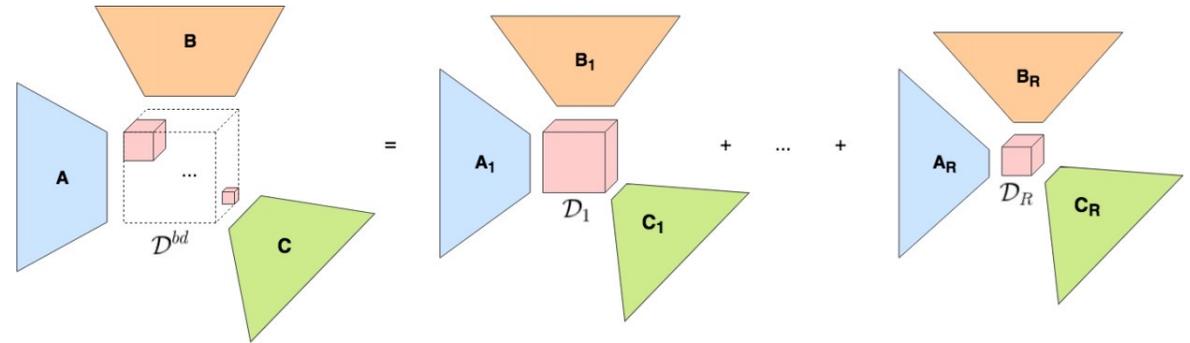
Laptops

What are on the shelves in the background?



Books

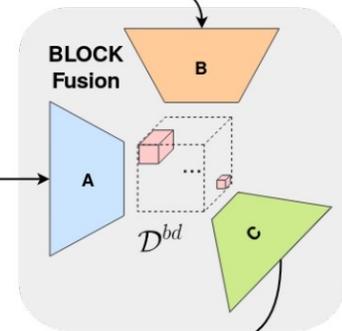
Multimodal Tucker Fusion



What is this person holding? → Question embedding



Image embedding



Classification

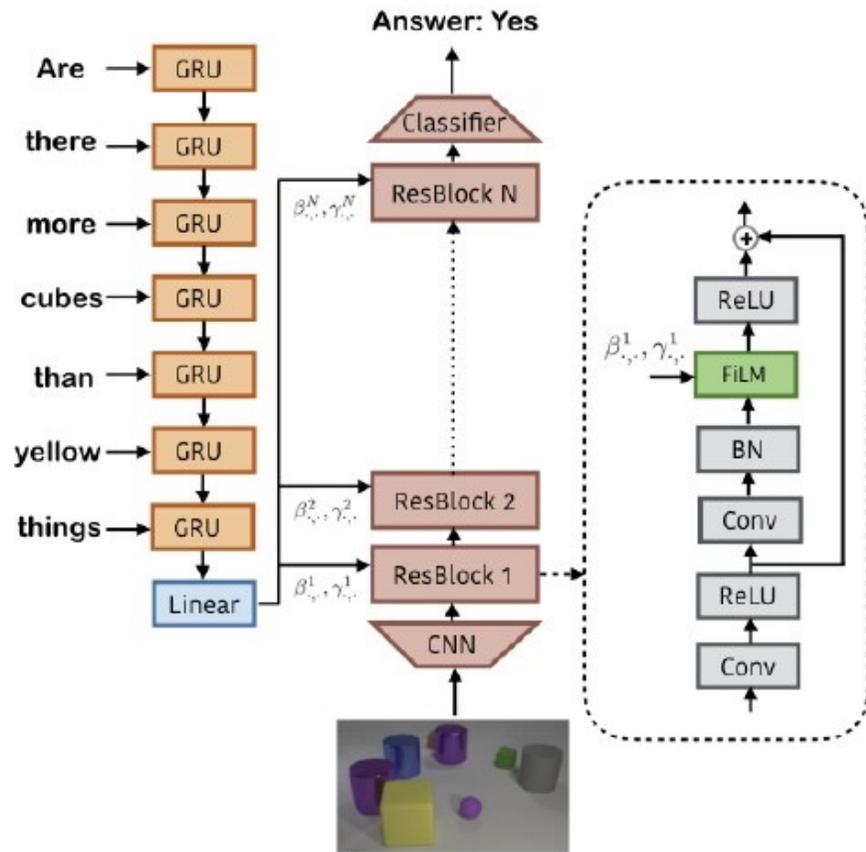
skis

Bilinear Super-diagonal Fusion

1 MUTAN: Multimodal Tucker Fusion for Visual Question Answering, ICCV 2017

2 BLOCK: Bilinear Superdiagonal Fusion for Visual Question Answering and Visual Relationship Detection, AAAI 2019

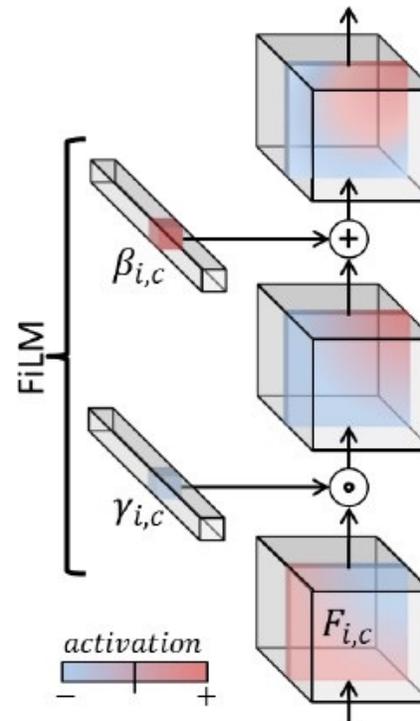
# FiLM: Feature-wise Linear Modulation



$$\gamma_{i,c} = f_c(\mathbf{x}_i) \quad \beta_{i,c} = h_c(\mathbf{x}_i),$$

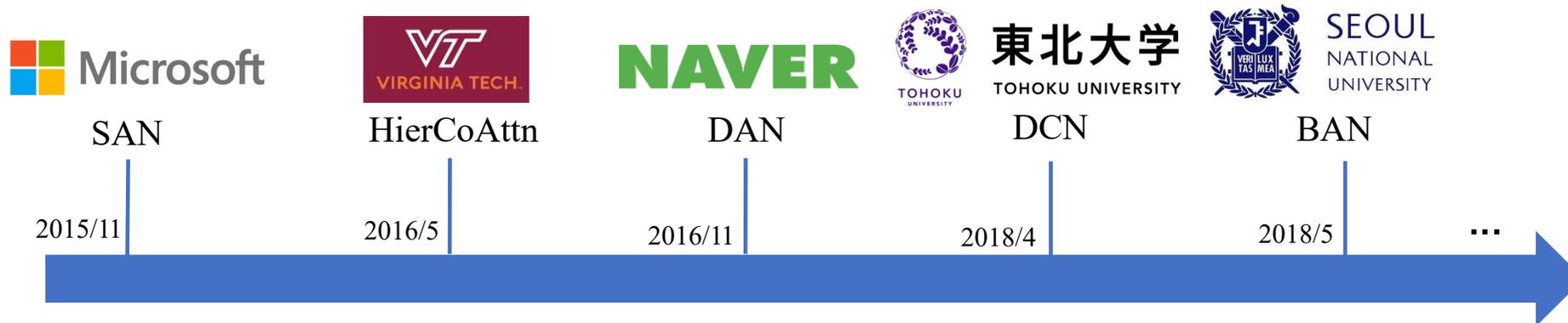
$$\text{FiLM}(\mathbf{F}_{i,c} | \gamma_{i,c}, \beta_{i,c}) = \gamma_{i,c} \mathbf{F}_{i,c} + \beta_{i,c}.$$

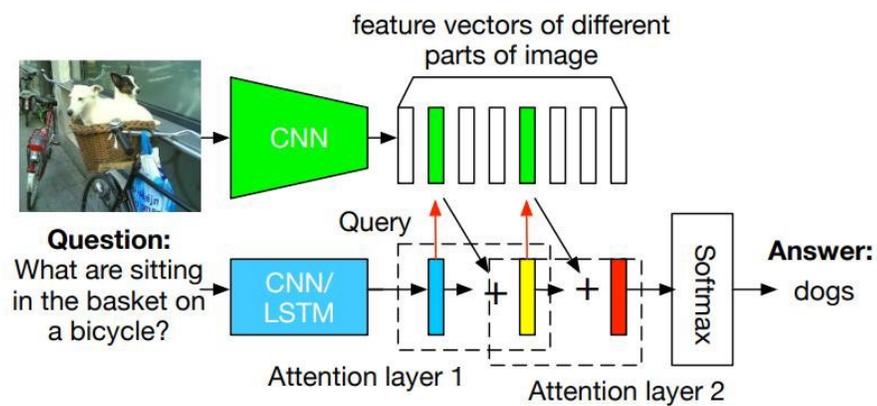
Something similar to conditional batch normalization



# Multimodal Alignment

- Cross-modal attention:
  - Tons of work in this area
  - Early work: questions attend to image grids/regions
  - Current focus: image-text co-attention



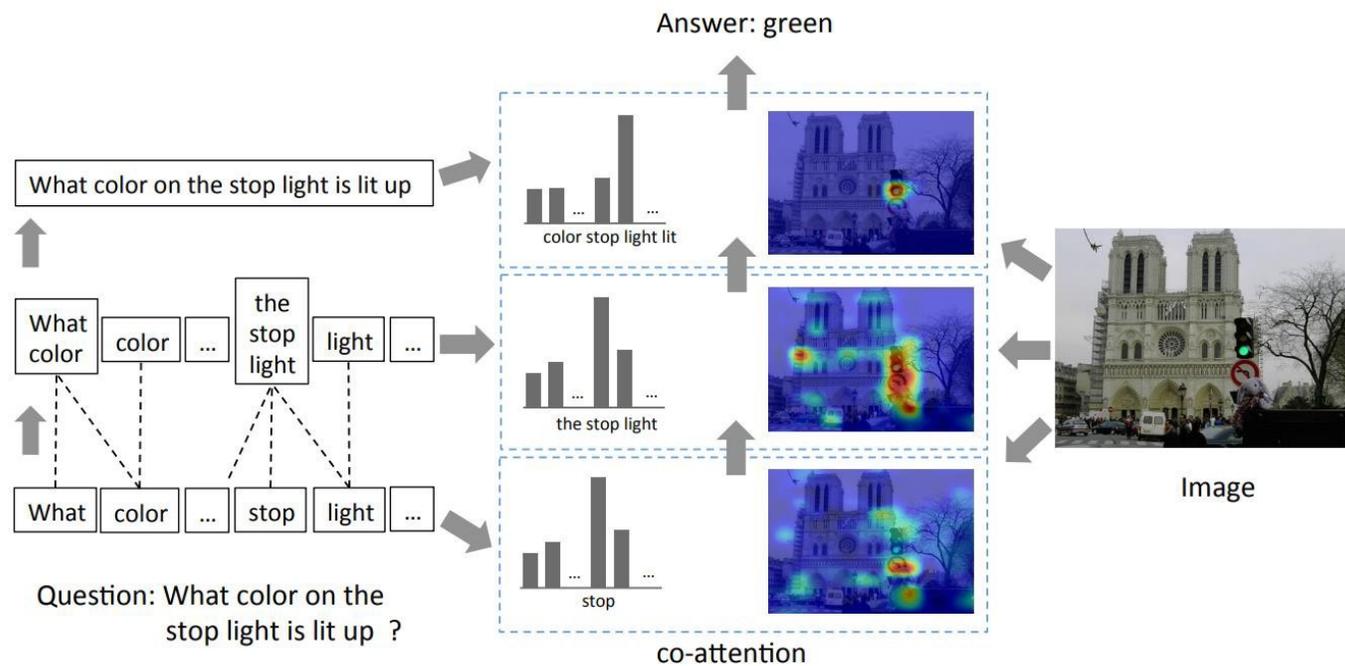


(a) Stacked Attention Network for Image QA



Original Image First Attention Layer Second Attention Layer

(b) Visualization of the learned multiple attention layers.



## Parallel Co-attention and Alternative Co-attention

- 1 Stacked Attention Networks for Image Question Answering, CVPR 2016
- 2 Hierarchical Question-Image Co-Attention for Visual Question Answering, NeurIPS 2016



SAN

2015/11



HierCoAttn

2016/5

NAVER

DAN

2016/11



東北大学  
TOHOKU UNIVERSITY

DCN

2018/4

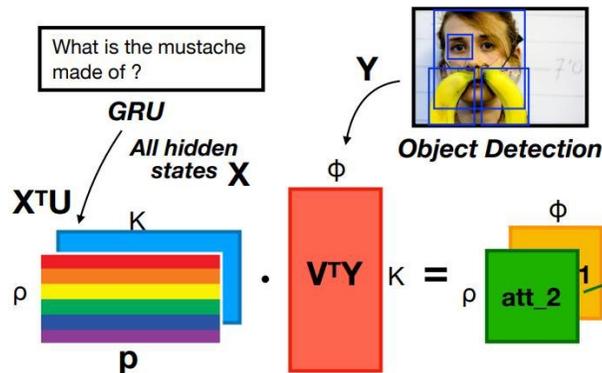
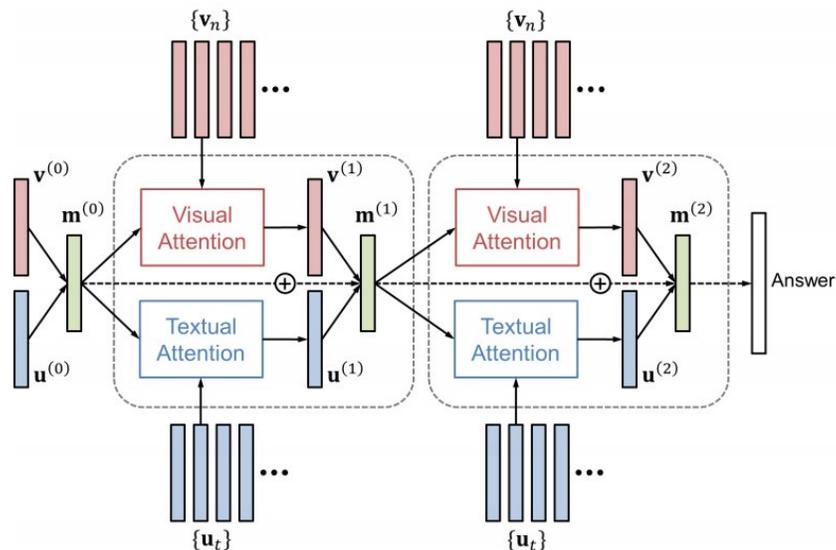


SEOUL  
NATIONAL  
UNIVERSITY

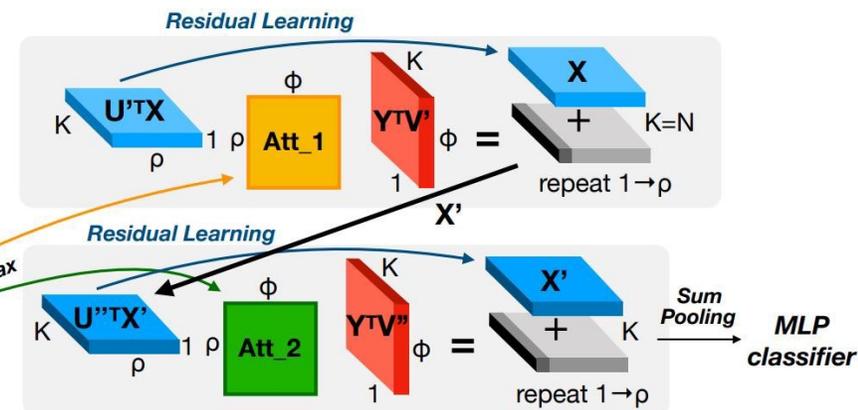
BAN

2018/5

...



Step 1. Bilinear Attention Maps



Step 2. Bilinear Attention Networks

### 2018 VQA Challenge Runner-Up

- Multiple Glimpses
- Counter Module
- Residual Learning
- Glove Embeddings

DAN: Dual Attention Network

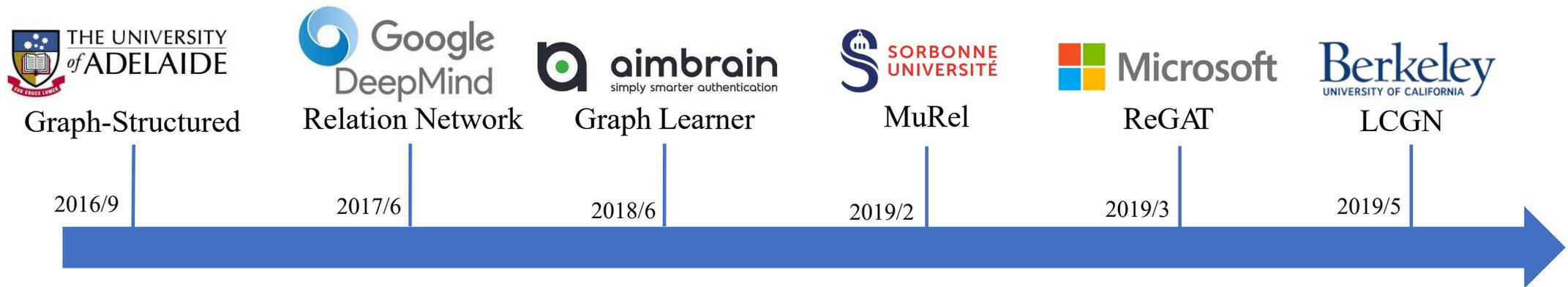
DCN: Dense Co-attention Network

1 Stacked Attention Networks for Image Question Answering, CVPR2016

2 Improved Fusion of Visual and Language Representations by Dense Symmetric Co-Attention for Visual Question Answering, CVPR2018

# Relational Reasoning

- Intra-modal attention
  - Recently becoming popular
  - Representing image as a graph
  - Graph Convolutional Network & Graph Attention Network
  - Self-attention used in Transformer





Graph-Structured

2016/9



2017/6



Graph Learner

2018/6



MuRel

2019/2



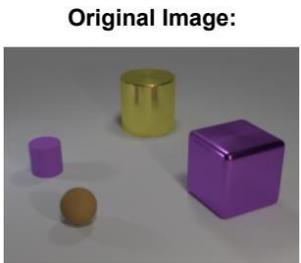
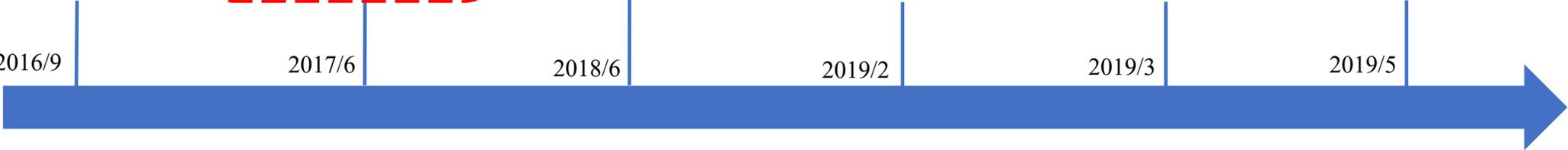
ReGAT

2019/3



LCGN

2019/5



Original Image:

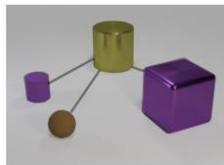
**Non-relational question:**

What is the size of the brown sphere?

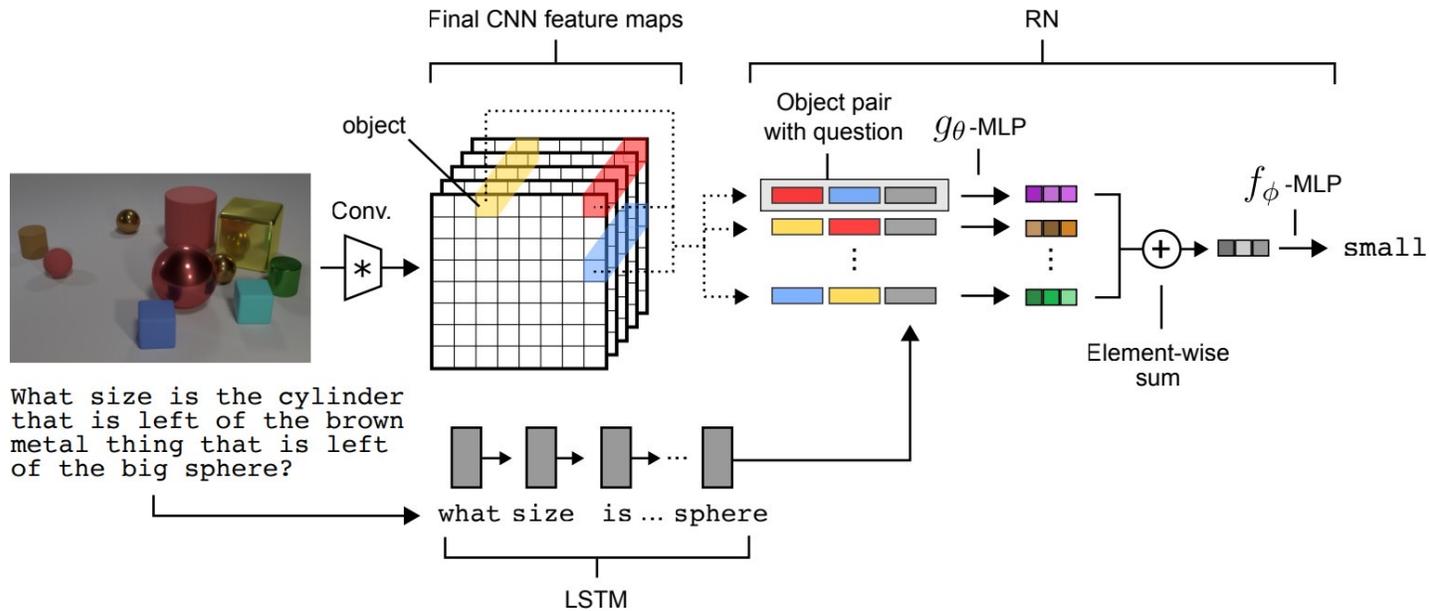


**Relational question:**

Are there any rubber things that have the same size as the yellow metallic cylinder?



$$RN(O) = f_{\phi} \left( \sum_{i,j} g_{\theta}(o_i, o_j) \right)$$



Relational Network: A fully-connected graph is constructed



Graph-Structured

2016/9



Relation Network

2017/6



Graph Learner

2018/6



MuRel

2019/2

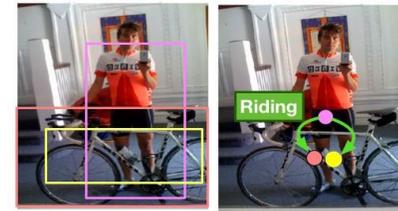
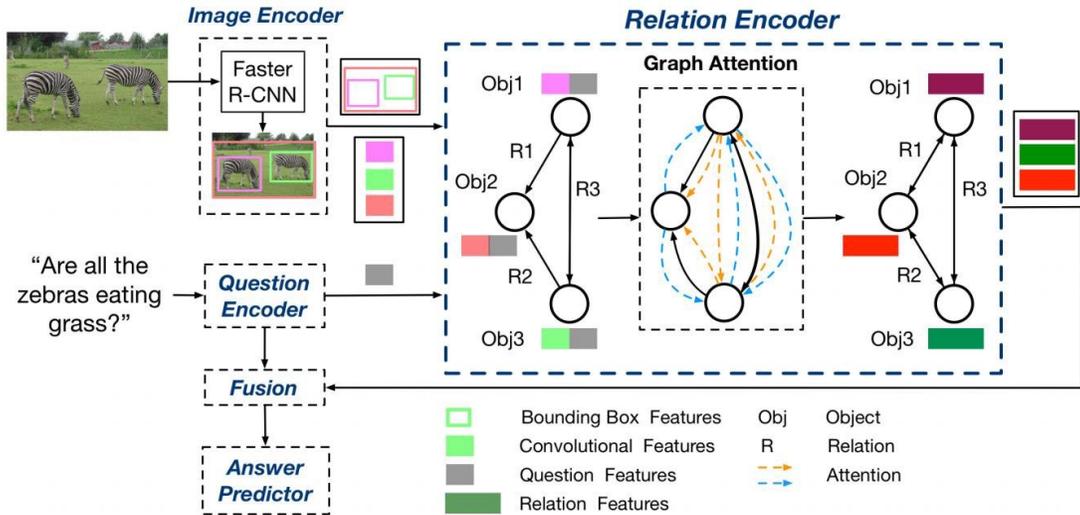


2019/3



LCGN

2019/5

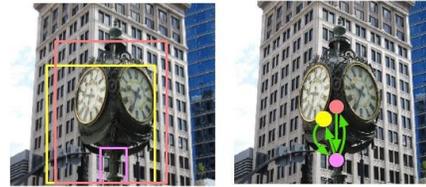


Q: Is this the typical fashion for riding this bike?  
A: Yes

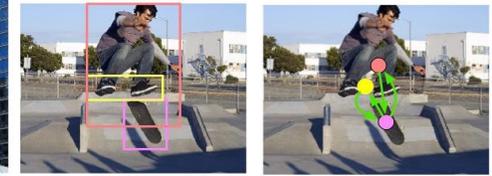


Q: What is he holding?  
A: Tennis Racket

(a) Semantic Relation

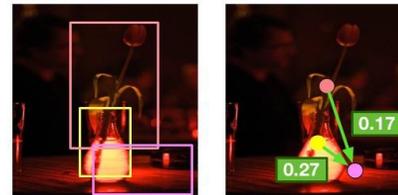


Q: What's the clock attached to?  
A: Pole



Q: Are his feet touching the skateboard?  
A: No

(b) Spatial Relation



Q: Where is the vase?  
A: On the table



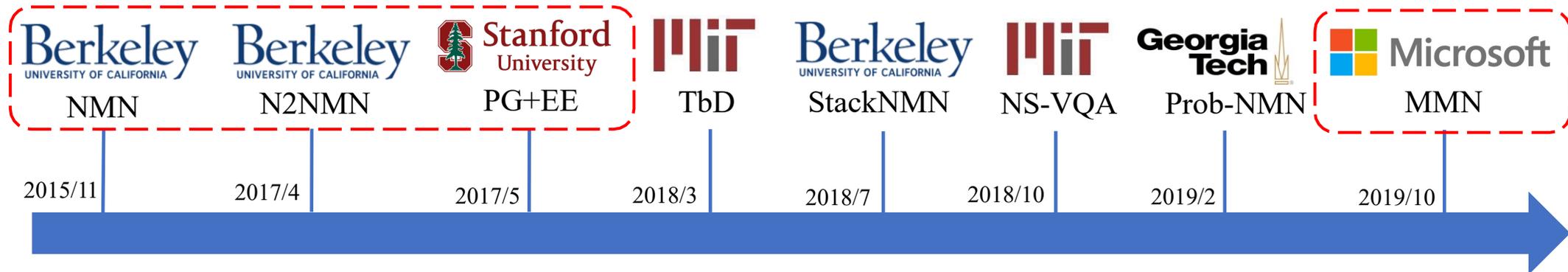
Q: Should the people be walking according to the light?  
A: No

(c) Implicit Relation

- Explicit Relation: Semantic & Spatial relation
- Implicit Relation: Learned dynamically during training

# Neural Module Network (NMN)

- All the previously mentioned work can be considered as [\*Monolithic Network\*](#)
- Design [\*Neural Modules\*](#) for compositional visual reasoning – very “human like”



- 1 Deep Compositional Question Answering with Neural Module Networks, CVPR, 2016
- 2 Learning to Reason: End-to-End Module Networks for Visual Question Answering, ICCV 2017
- 3 Inferring and Executing Programs for Visual Reasoning, ICCV 2017
- 4 Transparency by Design: Closing the Gap Between Performance and Interpretability in Visual Reasoning, CVPR 2018
- 5 Explainable Neural Computation via Stack Neural Module Networks, ECCV 2018
- 6 Neural-Symbolic VQA: Disentangling Reasoning from Vision and Language Understanding, NeurIPS 2018
- 7 Probabilistic Neural-symbolic Models for Interpretable Visual Question Answering, ICML 2019
- 8 Meta Module Network for Compositional Visual Reasoning, 2019

# Consider a compositional model

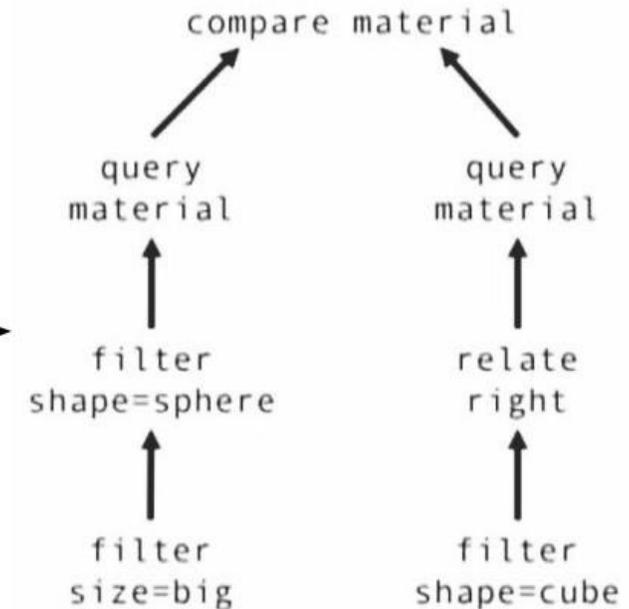
Q: How many spheres are the left of the big sphere and the same color as the small rubber cylinder?

Q: How many spheres are the right of the big sphere and the same color as the small rubber cylinder?

Q: Is the big sphere the same material as the thing on the right of the cube?

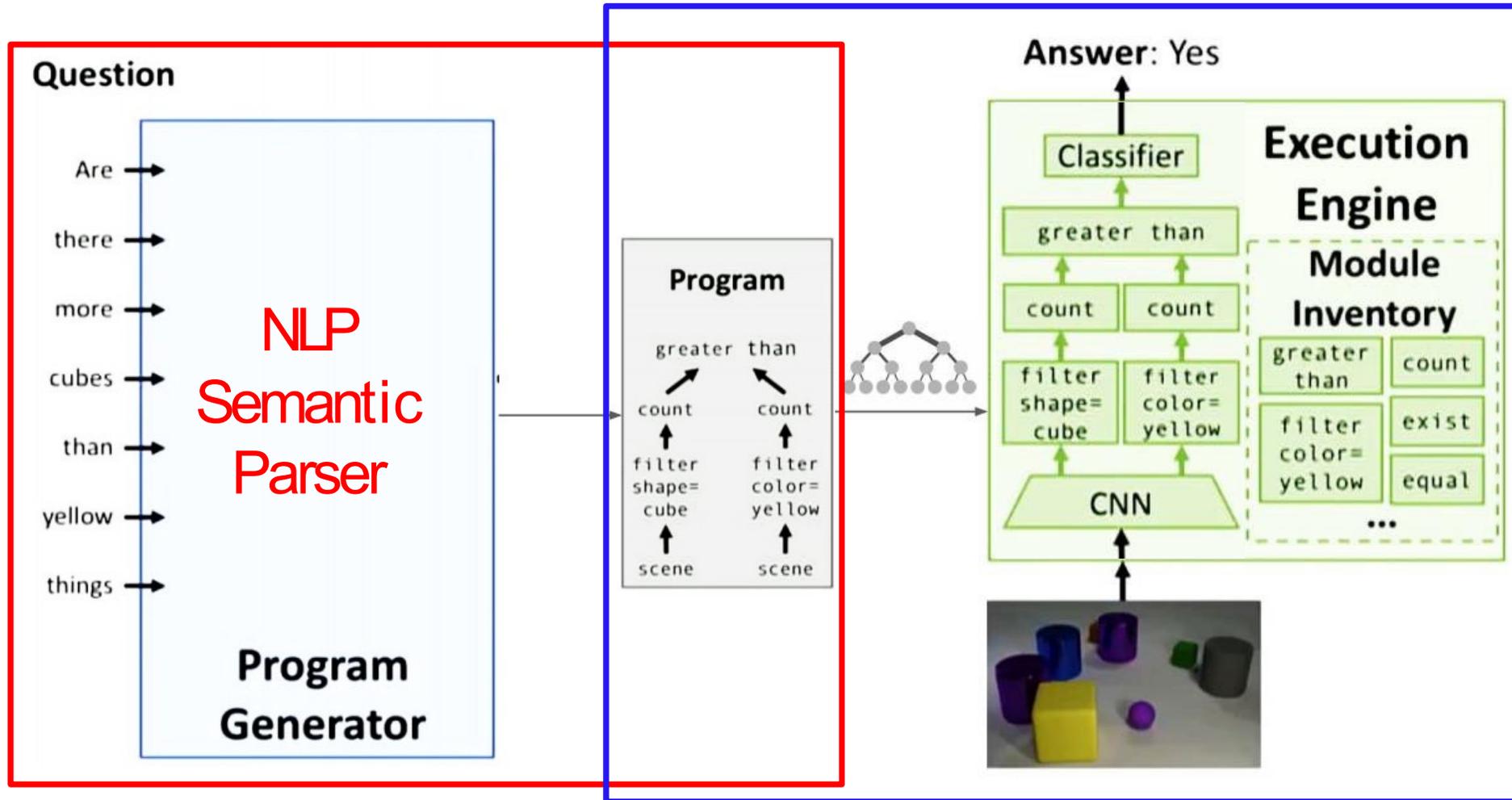
## Common operations

Attributes identification  
Counting objects  
Comparisons  
Spatial relationships  
Logical operations



Network architecture  
corresponding to the  
third question

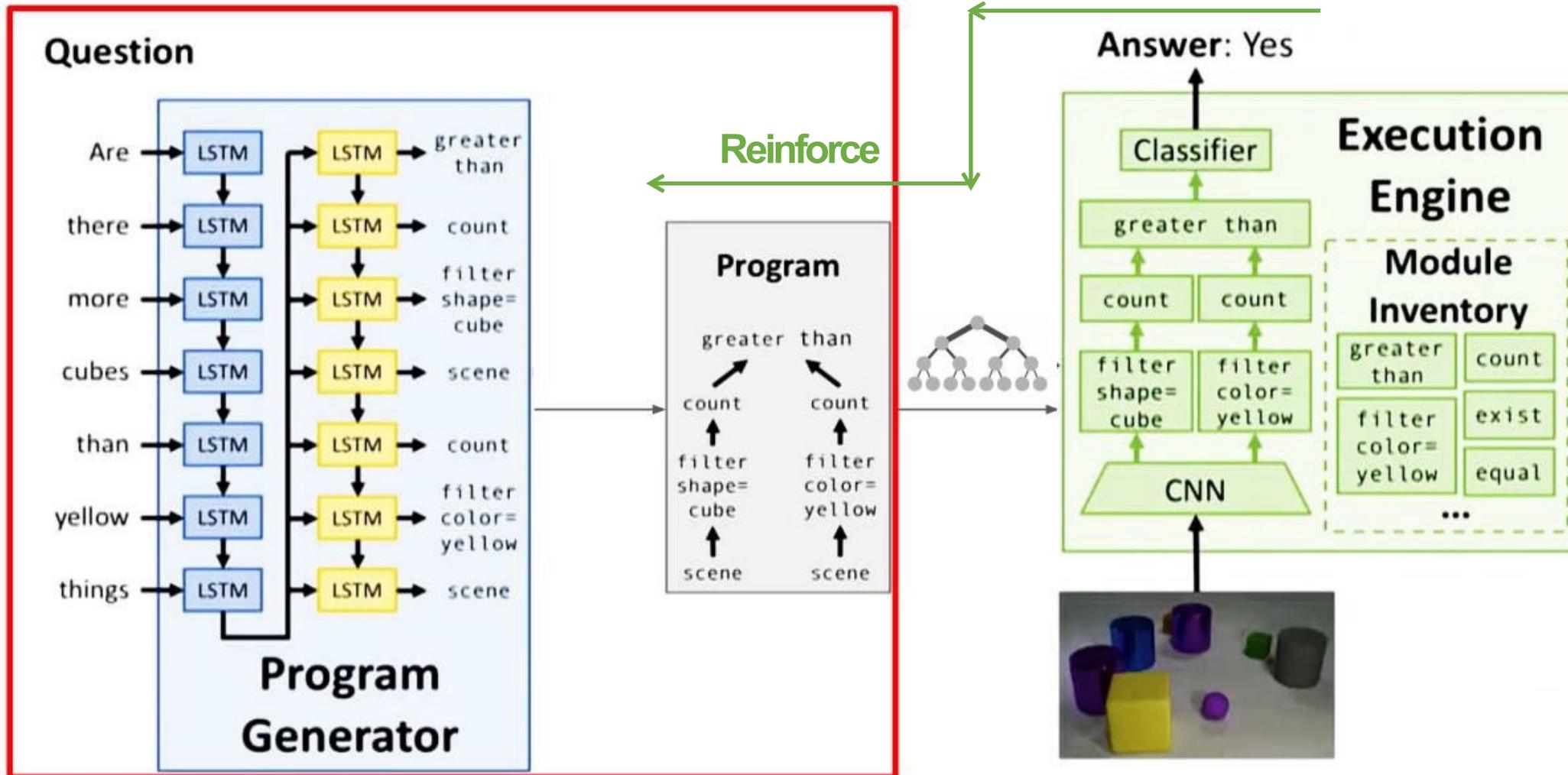
# Overview of the NMN approach

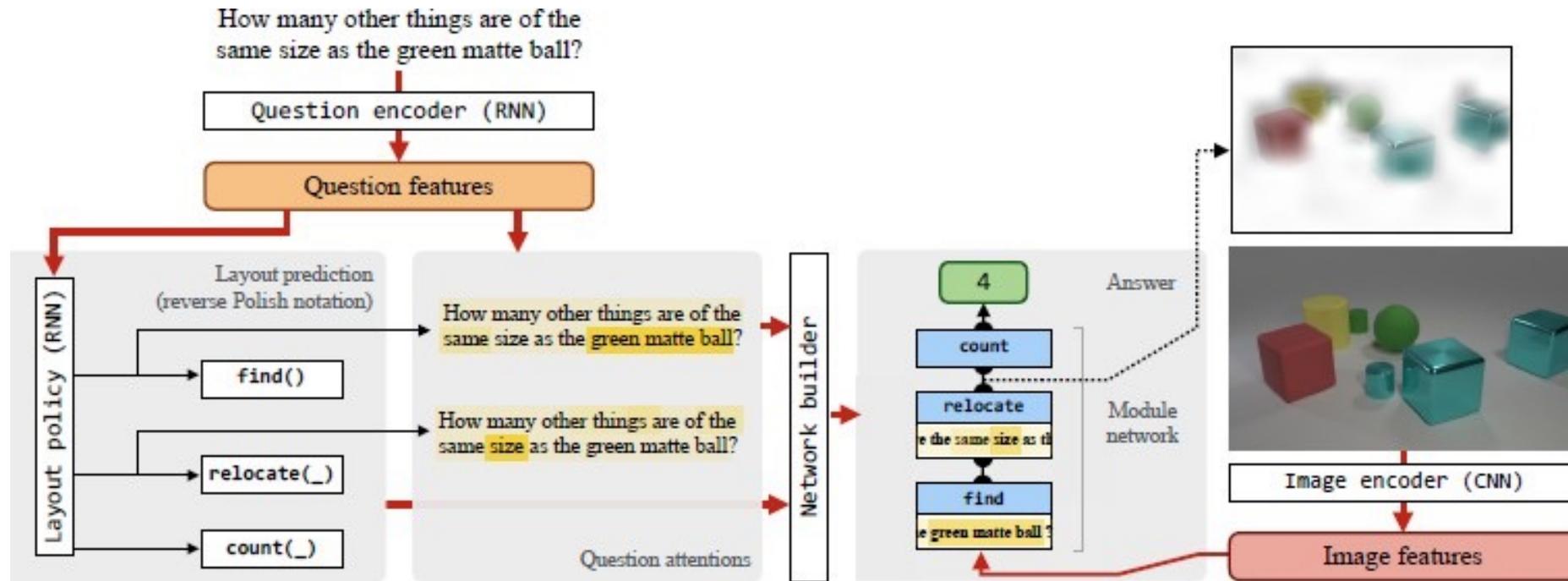
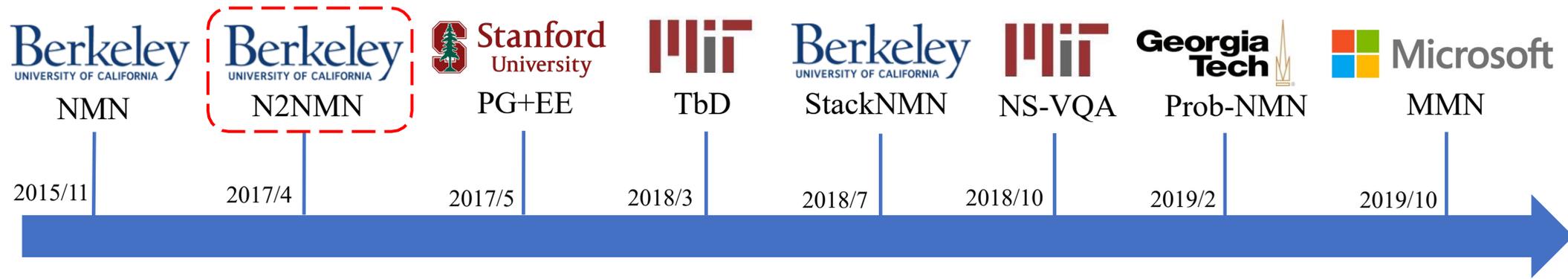


Uses some pre-trained parser

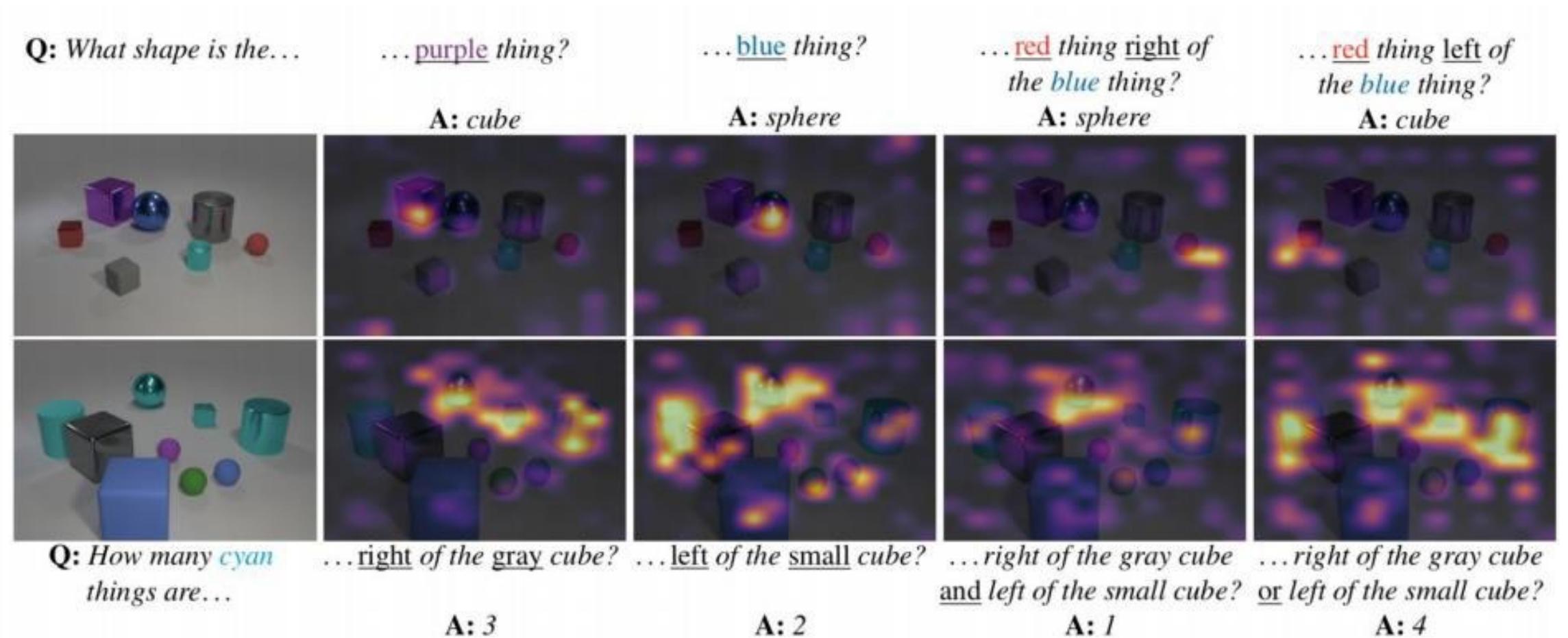
Trained separately

# Inferring and Executing Programs



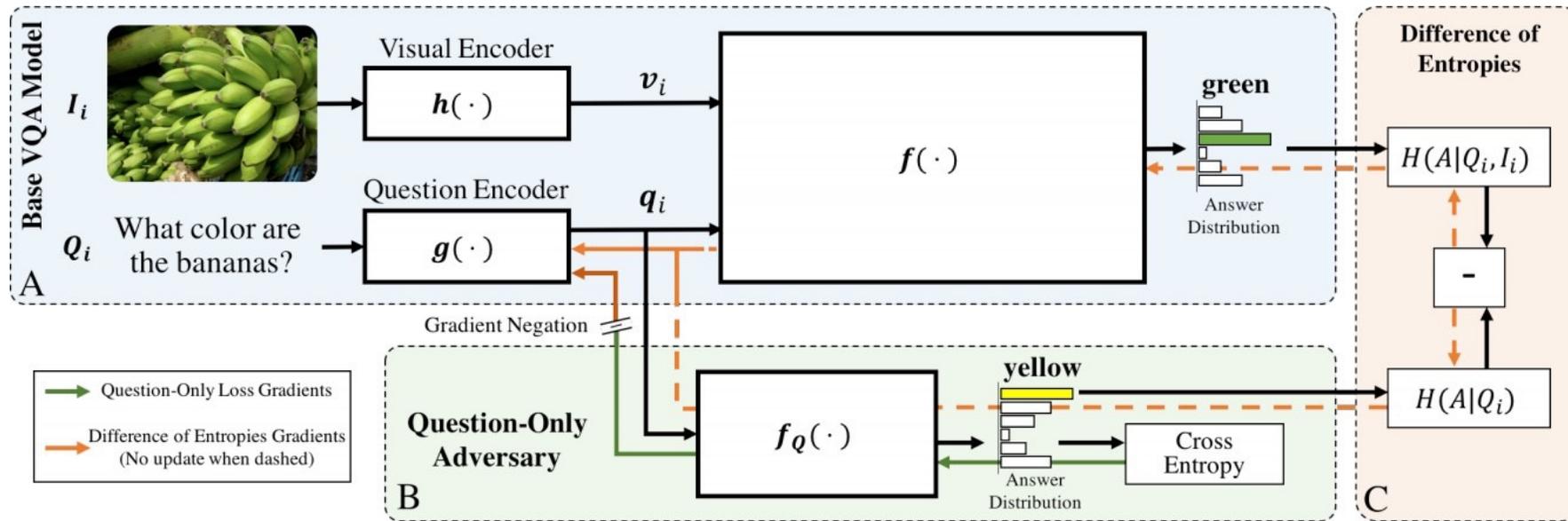


# What do the modules learn?



# Robust VQA: an example

- Overcoming language prior with adversarial regularization





The University of Texas at Austin  
**Electrical and Computer  
Engineering**  
*Cockrell School of Engineering*